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Secure Remote Control and Configuration of FPX Platform in Gigabit Ethernet Environment

Haoyu Song

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WASHINGTON UNIVERSITY SEVER INSTITUTE OF TECHNOLOGY DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING

SECURE REMOTE CONTROL AND CONFIGURATION OF THE FPX PLATFORM IN GIGABIT ETHERNET ENVIRONMENT

by

Haoyu Song

Prepared under the direction of Professor John W. Lockwood

A project report presented to the Sever Institute of Washington University in partial fulfillment of the requirements for the degree of

Master of Science

August, 2003

Saint Louis, Missouri

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Because of its flexibility and high performance, reconfigurable logic functions implemented on the *Field-programable Port Extender* (*FPX*) are well suited for implementing network processing such as packet classification, filtering and intrusion detection functions. This project focuses on two key aspects of the *FPX* system. One is providing a *Gigabit Ethernet* interface by designing logic for a *FPGA* which is located on a line card. *Address Resolution Protocol* (*ARP*) packets are handled in hardware and *Ethernet* frames are processed and transformed into cells suitable for standard *FPX* application.

The other effort is to provide a secure channel to enable remote control and configuration of the FPX system through public internet. A suite of security hard-ware cores were implemented that include the Advanced Encryption Standard (AES),

Triple Data Encryption Standard (3DES), Hashed Message Authentication Code (HMAC), Message Digest Version 5 (MD5) and Secure Hash Algorithm (SHA-1). An architecture and an associated protocol have been developed which provide a secure communication channel between a control console and a hardware-based reconfigurable network node. This solution is unique in that it does not require a software process to run on the network stack, so that it has both higher performance and prevents the node from being hacked using traditional vulnerabilities found in common operating systems. The mechanism can be applied to the design and implementation of remotely managed FPX systems. A hardware module called the Secure Control Packet *Processor* (SCPP) has been designed for a FPX based firewall. It utilizes AES or 3DES in Error Propagation Block Chaining (EPBC) mode to ensure data confidentiality and data integrity. There is also an authenticated engine that uses HMACto generate the acknowledgments. The system can protect the FPX system against attacks that may be sent over the control and configuration channel. Based on this infrastructure, an enhanced protocol is addressed that provides higher efficiency and can defend against replay attack. To support that, a control cell encryption module was designed and tested in the FPX system.

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Haoyu Song

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Chapter 1

Motivation

As the Internet grows, more and more networking applications will use reconfigurable hardware devices to provide both high performance and flexibility. The *Field*programable Port Extender (FPX) is an open, reconfigurable, high performance and extensible IP packet processing platform [24][23]. It processes packets in hardware to perform content filtering, intrusion detection and other customizable functions. All logic on the FPX is implemented in FPGAs. FPGAs accelerate processing while preserving flexibility. Several packet processing engines can be deployed in parallel or in pipelines, and it is possible to achieve multiple gigabit per second throughput.

The FPX platform is highly reconfigurable. New bitfiles can be downloaded on demand within seconds and start being tested at once. Moreover, the hardware can be reprogrammed via the Internet without physical access to the device. Consequently, remote control and configuration of the FPX are feasible and convenient for a network administrator.

The FPX platform can be deployed throughout a backbone network or at an access point to an enterprise network. Gigabit rate network links are common today. To meet this bandwidth requirement, the FPX has a broadband line interface. To allow the *FPX* to be easily connected to standard networks, a *Gigabit Ethernet* interface was implemented. *Ethernet* is an evolving technology that will play an important role not only in *Local Area Networks* (*LANs*) but also in *Wide Area Networks* (*WANs*).

Secure control and configuration of the FPX system are needed to enable deployment of FPX systems throughout the public Internet. Run time reconfiguration allows dynamic hardware plugins to be sent over networks and to update the functions on the FPX. It is envisioned that the FPX system will be distributed over large geographic areas and operate over public networks, making on-site configuration and management infeasible. The security of the remote control and configuration is a serious concern. Robust security mechanisms are needed to protect the reconfigurable network nodes from unauthorized access and to ensure the integrity of reconfiguration when being reprogrammed over the network.

1.1 Background

1.1.1 FPX Platform

The logic of the FPX is implemented within two FPGAs: the *Reconfigurable Application Device* (*RAD*) which is used to prototype new networking functions and protocols, and the *Network Interface Device* (*NID*) which is used to interface between the line card and *RAD*.

The *FPX* platform can act as a network monitor to screen and analyze the traffic passing through the Internet. It can also actively process the traffic using predefined policies. *Global Velocity* has found one such application for copyright-protected content

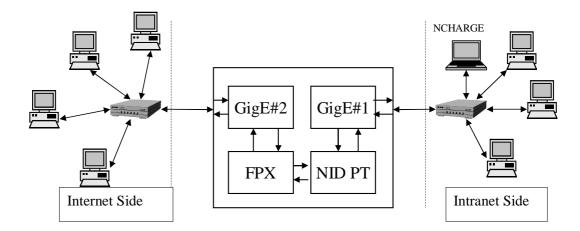


Figure 1.1: FPX in a box

on a network. The FPX can also be used to scan and block viruses and Internet worms.

Two FPX cards and two line cards are used in a FPX standalone platform as is shown in Figure 1.1. The side on which the control console is attached is defined as the *Intranet* side. Notice that it is unnecessary for the control console to be directly connected to the box. Since the box is Internet addressable, control packets can be issued remotely. On the *Intranet* side, the *NID* on the *FPX* card is configured to pass through traffic (*NID-PT*). It is responsible for extracting and encapsulating packets that pass through the network. The other side of the *FPX* platform is called the *Internet* side. On this side, there sits a regular *FPX* card which monitors or processes the packets. For historical reasons, the basic unit processed in *FPX* is an *ATM* cell. Internet packets are encapsulated into *AAL5* frames. A suite of protocol wrappers were designed to process data at different protocol layers.

The FPX platform works at gigabit-per-second link speed. The Gigabit Ethernet line card interface allows the FPX to sit in an Ethernet LAN and work in both passive and active modes. The line card has a Gigabit Ethernet Controller Application Specific Integrated Circuit, the PM3386~S/UNI-2xGE [44]. The PM3386 is a monolithic ASIC that implements full-duplex 1000 Mbps Ethernet~MAC transport function. The PM3386 provides connectivity to an on-chip SERialize/DESerialize(SERDES) and Gigabit~Media~Independent~Interface~GMII functions. It also provides a data transport interface to the up stream device via an industry standard POS-PHY~Level~3 interface. The system's backplane connector sends and receives data formatted in ATM cells. In order to translate between ATM cells and EthernetMAC frames, an extra circuit is needed. A Xilinx FPGA~XC2V1000 [45] is arranged on the line card to implement those functionalities. The XC2V1000 belongs to the Xilinx VIRTEX-II family. It has what is called the equivalent of 1M system gates and also has 160 Kbits of block RAM. These resources are enough to implement packet processing functions needed for the circuit.

The initial version of the FPX platform did not use any encrypted mechanism to control and configure the hardware. There is an urgent requirement to add this functionality in order to make the FPX reliable and secure in a public network.

1.1.2 Gigabit Ethernet Processing

Ethernet has been the dominant LAN technology since the early 1970s. Gigabit Ethernet is built on top of the Ethernet protocol, but increases speed tenfold over Fast Ethernet to 1 Gbps. This protocol, which was standardized in June 1998, promises to be a dominant technology for high-speed local area network backbones and server connectivity. Reference [39] gives a detailed technology review of Gigabit Ethernet.

Ethernet uses a 48-bit physical address to identify each node. Each frame has a 14-byte MAC header which includes a 6-byte destination address, a 6-byte source

Normal Ethernet Frame

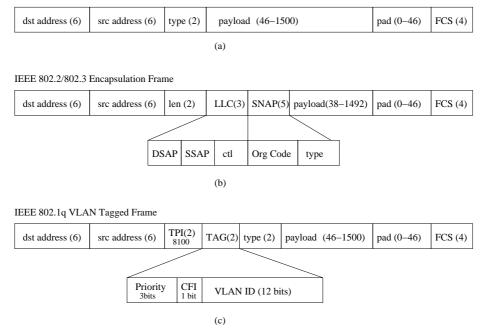


Figure 1.2: Ethernet Frame Format

address and 2 bytes payload type field (In *Ethernet V2*, this field is also defined as payload length field if the value is greater than 1500). Figure 1.2(a) shows a typical *Ethernet* frame as defined in *RFC894*. *IEEE 802.2* also defines a *LLC/SNAP* field for the *Ethernet* header, as shown in Figure 1.2(b). Figure 1.2(c) shows another type of an *Ethernet* frame which is defined in *IEEE 802.1q* known as *Virtual LAN* (*VLAN*) field. A *VLAN* can be viewed as a group of devices on different physical *LAN* segments which can communicate with each other as if they were all on the same physical *LAN* segment. Networks can have differential classes of service (*COS*) functions based on the value of the *VLAN ID* and the service priority. *VLAN* technology enables flexible network segmentation by assigning different *VLAN IDs* to the different subnetworks. It improves network management by managing the logical *LAN* instead of the physical *LAN* and increases the performance by isolating the broadcast domains and enforcing the *COS*. It also enhances the network security by limiting the extent to which packets are broadcast. In our application, we use *Ethernet* to carry *IP* packets. One key protocol is the Address Resolution Protocol (ARP)[35]. Whenever an *IP* packet is ready to be forwarded in an *Ethernet* frame over the network, the directly connected host or gateway router's physical address must be resolved using the destination *IP* address. To resolve a forwarding *IP* address to its *MAC* address, *ARP* sends out a broadcast frame called an *ARP Request* on the shared media. Any host or router which has the requested *IP* address or is responsible for that address will send back to the sender an *ARP Reply* which contains the *MAC* address corresponding to the desired forwarding *IP* address.

An ARP cache is maintained in order to keep the number of broadcast ARPRequest frames to a minimum. Recently resolved IP addresses and their corresponding MAC addresses are stored in a table. The ARP cache is checked first before sending an ARP Request frame. Only when there is not a matched entry will an ARP Request packet be sent. ARP cache entries can either be dynamic (based on ARP Replies) or static (if configured manually). Static ARP cache entries are used to prevent ARP Requests from being broadcast for commonly-used local IP addresses, such as routers and servers. The problem with static ARP entries is that they have to be manually updated when network interface equipment changes. Dynamic ARPcache entries have a time-out value associated with them so that entries are removed form the cache after a specified period of time. The ARP packet format is shown in Figure 1.3.

1.1.3 Network Security and Cryptography

Although we enjoy the abundant information available on open networks, when we use the Internet, we also face the threat of being infected with a virus, or having

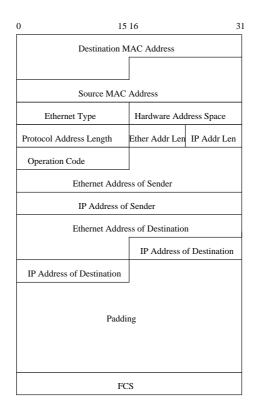


Figure 1.3: Address Resolution Protocol Frame Format

our machine hacked. The growth of the Internet requires us to protect both our infrastructure and information from malicious attacks.

In general, attacks can be classified into two major categories: *Denial-of-Service* (*DOS*) and *Unauthorized Access*. For a *DoS* attack, the attacking host(s) sends more requests to a target machine than it can handle. Usually the source of the attack is hard to trace. *Unauthorized Access* includes eavesdropping, transmission of fake data, replay of previously sent messages and data destruction. Cryptography can provide protection against many types of attacks at a reasonable cost. Many encryption and authentication algorithms have been developed and are widely used in network security as well as in other fields.

There are two common types of encryption algorithms. The first type uses private-keys (also called symmetric-keys) which only have one unique key for both encryption and decryption; the other type uses public and private key-pairs (also called asymmetric-keys). Basic attributes of encryption technologies are *confusion* and *diffusion* [41]. *Confusion* intends to make the relationship between the statistics of the ciphertext and the value of the encryption key as complex as possible. *Diffusion* seeks to make the statistical relationship between the plaintext and ciphertext as complex as possible. For an ideal algorithm, the security depends only on the secret key.

The Data Encryption Standard (DES) [30] was developed by an IBM team and adopted as a national standard in 1977. Despite the growing concerns about its vulnerability, DES is still widely used to protect sensitive online applications. 3DES is a variation of this standard that can be billions of times more secure if used properly. The procedure of 3DES encryption is exactly the same as regular DES, except that DES is repeated three times. In 2000, National Institute of Standards and Technology (NIST) selected the Rijndael algorithm as the proposed Advanced Encryption Standard (AES) [31] for protecting data through encryption. In addition to the increased security that comes with larger key sizes, AES can encrypt data much faster than 3DES.

Most of the private-key algorithms are perfectly suited for hardware implementation due to their regular structure and bit-wise operations used to encrypt data. Many cipher modes can be applied to provide extra security for some kinds of attacks or to protect data integrity. Some classic modes are *Electronic Codebook Mode* (ECB), *Cipher Block Chain Mode* (CBC), *Output Feedback Mode* (OFB), *Cipher Feedback Mode* (CFB) and *Counter Mode* (CTR). All of these modes have their own advantages and disadvantages for different applications. Some novel modes provide interesting and more secure features [1][32]. Public-key or asymmetric-key encryption algorithms use two different keys for encryption and decryption. A key pair is generated and a public key is used to encrypt messages and the ciphertext can only be decrypted with a private key. For a good encryption algorithm, it is very difficult to determine the private key given the public key. This type of algorithms can also be used for digital signatures, authentication and key distribution. One popular algorithm in this category is the *Rivest-Shamir-Adleman* (*RSA*), named after the researchers who developed it [41]. Since asymmetric algorithms are relatively slow, they are seldom used for encryption of large amounts of data.

Though encryption itself can provide authentication to some extent, a keyed hash function is preferred for that function. Algorithms such as *Message Digest Version 5 (MD5)* or *Secure Hash Algorithm (SHA-1)* can generate the digest of a message. *Hashed Message Authentication Code (HMAC)* embeds these hash functions into what is called a "black box" to have the last digest code only depend on a secret key [22]. Since it was published in *RFC2104*, *HMAC* has become the most popular method of data authentication.

Firewall technologies and network intrusion detection devices are now widely deployed in organizations and corporations. They audit and classify packets to detect and prevent harmful attacks. In order to keep up with the explosive growth of the network bandwidth, encryption and decryption tasks must be performed in hardware. Reconfiguable hardware is especially well-suited for the implementation of such network processing functions.

1.2 Contributions of This Work

The logic that controls a *Gigabit Ethernet* line card has been implemented on an FPGA and verified to work with the FPX platform. Another version was designed for the *Multi-Service Router* (*MSR*) project, where the line card is mainly used in the Washington University Gigabit Switch (WUGS).

A Secure Control Packet Processor (SCPP) for dynamic configuration of the FPX has been designed and verified. The module implements several IPSec standards including AES, 3DES and HMAC using either MD5 or SHA-1. A secure acknowledgement protocol was designed so that the FPX platform can be securely configured remotely via the Internet.

Based on this infrastructure, the security of the FPX platform was enhanced by introducing a secure protocol with a secure communication channel between a control console and an FPX platform. This solution is unique in that it runs in hardware on the end system, so that it has both higher performance and safety as compared to protocol stacks implemented in software atop an operating system. This secure control scheme can also prevent replay attacks.

1.3 Related Work

An Internet Protocol (IP) stack implemented in reconfigurable hardware is used to process packets [6]. It includes a set of layered wrappers which process ATM cells, AAL5 frames, and IP and UDP packets. An ARP engine was implemented so that the system can work in LAN environment. Other projects implemented ARP as part of IP stack. The protocol stack described in [33] is limited to 10Mb/s Ethernet operation. It implements the lower layers of a protocol stack and only supports IP and ARP functions.

Symmetric-key encryption algorithms and message digest hash functions are widely used for network security. Many of them are well-suited for hardware implementation. There are many papers that discuss FPGA implementations of AES, DES, HMAC and other security algorithms [16][9][14][17]. These kinds of hardware designs are all tradeoff between the throughput and the circuit area. Usually, iteration unrolling and pipeline technologies are used to improve the throughput. To optimize the area, iteration rolling is used at the expense of throughput degradation.

For secure remote control, S. Gultchev et. al. presented a secured Reconfigurable Management Architecture (RMA) to enforce robust security mechanisms on mobile Software Radio Terminals [37]. Due to the heavy computation cost, this scheme is inefficient to implement in a pure hardware environment. The low data throughput makes it unsuitable for high-speed data communication. R. Chakravorty et. al. presented a Smart Box Management (SBM) - an end-to-end remote management framework for Internet enabled devices [7]. Though this work is focused on a software framework, it provides a good framework for remote device manage-While many of the network management technologies today only monitor ment. nodes, the MIDAS project by S.N.Bhatti et. al. offers management capability for a large distributed system [4]. Other work done by J. Forne, et. al. presents a solution providing secure communications over an extended *Ethernet LAN* [27]. Most of the works listed above focus on development of a software-based security framework and involve a huge computational effort, which can cause unbearable overhead and bottleneck performance for applications such as programmable network routers, sensors, and firewalls.

1.4 Outline

The thesis is organized as follows. Chapter 2 presents the design, verification and performance evaluation of the logic for a *Gigabit Ethernet* line card implemented in an *FPGA*. *ARP* processing and packet transformation are discussed in detail. Chapter 3 discusses the design of some cryptographic modules and their application in the *SCPP* structure for secure remote control of a *FPX*-based firewall, including a review of the implementation of the *AES*, *3DES*, *HMAC* and a specific mode, *Error Propagation Block Chaining (EPBC)*. In chapter 4, a more secure configuration protocol is proposed which enables the *FPX* platform to provide a secure control and configuration interface for general application. Finally, Chapter 5 concludes with a summary and a discussion of future work.

Chapter 2

Gigabit Ethernet Line Card FPGA

2.1 Protocol Stack

The protocol stack used in the FPX platform is shown in Figure 2.1. On the line side, IP packets are transmitted over *Gigabit Ethernet*; On the system side, IP packets are formatted into AAL5 frames and split into ATM cells.

The ATM cell has a fixed and short length that makes it suitable for fast switching and processing functions. One ATM cell has a 5-byte header and a 48byte payload. The routing information is indicated by *Virtual Path Identifier* (*VPI*) and *Virtual Circuit Identifier* (*VCI*) fields in ATM header. Header Error Control (*HEC*), the last byte of the header, is used to control the header's correctness. AAL5is designed for packet transmission and is widely used to transport Internet Protocol data. In AAL5, a frame with an arbitrary length is put into a *Protocol Data Unit* (*PDU*). In this design, we implemented classical *IP* over ATM. A *PDU*'s length is a multiple of 48 octets. One bit in the *Payload Type Identifier* (*PTI*) field of the ATM header is used to indicate whether a cell is the last one of a *PDU*. The last 8 octets of the *PDU* are used as a trailer, which contain the information about the

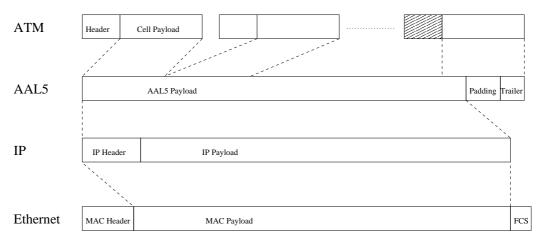


Figure 2.1: FPX in a box Protocol Stack

actual length of the payload data and a 32-bit CRC to ensure data integrity. Any gap between the frame and the trailer is filled with padding. Since PDUs are multiples of 48 octets, the trailer always ends at a cell's boundary and can therefore be located. The segmentation of frames with AAL5 and ATM cell's format are illustrated in Figure 2.2.

2.2 Architecture

The two major tasks of the *Gigabit Ethernet* (*GigE*) *FPGA* are to translate protocols and to perform ARP. The hardware logic must act as a bridge between ATMand *Ethernet* networks, handle both ARP request and reply, and maintain an ARPtable. Further, *IEEE802.1q VLANs* are also supported to make it flexible in different application environments. Figure 2.3 shows the overall structure of the *FPGA* circuit.

2.2.1 Cell and Frame Wrapper

The cell and frame wrapper module is part of "Layered Protocol Wrappers" [6][5], that are a collection of VHDL components processing high-level Internet protocols directly

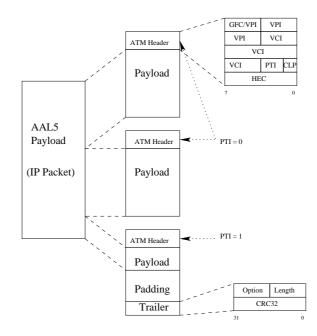


Figure 2.2: AAL5 to ATM mapping

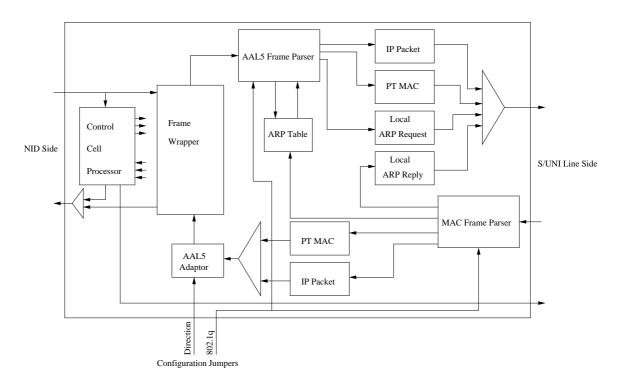


Figure 2.3: GigE FPGA Block Diagram

in hardware. The hardware library has four components that are used together to transmit and receive: fixed-length cells (ATM), variable-length AAL5 frames, IP packets and User Datagram Protocol (UDP) frames. They are primarily designed for the FPX, but could be also used in any hardware design. The ATM cell wrapper and the AAL5 frame wrappers are used in the implementation of the Gigabit Ethernet circuit design.

Incoming ATM cells from the FPX system side uses a signal Start Of Cell (SOC) to delimit the cells. The HEC is calculated and compared for every cell to check the cell's validity. If the check fails, the cell is dropped. Only valid cells are passed to the AAL5 Frame Wrapper. The Frame Wrapper extracts the AAL5 frames from the incoming cell stream, strips off any padding data, calculates AAL5 Frame Checksum (FCS) to verify the frame integrity and marks error frames. The Frame Wrapper replaces the SOC signal with three signals, namely Start of Frame (SOF), End Of Frame (EOF) and Data Enable (DataEN). The AAL5 frame data is sent to the Egress MAC module for processing.

An incoming AAL5 frame from the *Ingress MAC* module is segmented to a series of 48-byte data chunks in order to fit them into ATM cells. The remainder is padded with some zeros to make the size fit into one cell obeying the frame length information provided by *Ingress MAC* module. The *Frame Wrapper* calculates the frame *FCS* and then appends it as the *AAL5* frame trailer. The *ATM* cells are passed to *Cell Wrapper* from *Frame Wrapper*. The *Cell Wrapper* calculates *HEC*, fills it in *Header* for each cell and then forwards the cells to system side.

2.2.2 Control Cell Processor and Line Card Self-Configuration

A Control Cell Processor (CCP) block is used to receive control cells from the system side and extract the control commands to configure both FPGA and GigE controller ASIC. The configurations include the GigE line card's MAC address, IP address and mask, ARP table and initialization of the GigE ASIC. Through CCP a control host can also read back all the statistics counters and any ARP table entry.

To enable the system to bootstrap itself, a set of initialization control cells are stored in an on-chip *Read Only Memory* (ROM). When the system boots up, the cells are automatically injected into the *CCP*. Thus, the whole line card is configured and the system can immediately operate without any outside control.

2.2.3 ARP Lookup Table and Processing

An on-chip synchronous dual port *Random Access Memory* (*RAM*) was used to implement the ARP lookup table. The *Egress MAC* module performs read operations and *Ingress MAC* module performs write operations. The *CCP* can also access the table for debugging purposes or manual configuration.

In order to not interrupt the system's normal operation, the CCP has lower priority to access the table. When the CCP issues a write or read operation, if it happens that MAC modules are doing a similar operation, the operation from the CCP is paused and will not be processed until the operation from MAC modules is finished. Because two similar operation requests from the MAC modules have such long intervals from the point of view of the system, it is safe to perform the operation request from CCP after current operation from MAC modules. So at most 3 cycles after issuing the read request, the CCP can get the table output. Likewise, at most 3 cycles after issuing the write request, the data must have already been written into the table.

Ideally, an ARP lookup table should be able to handle any number of valid IP addresses and MAC addresses pair. But, in order to do this, an ARP lookup engine may need to scan a very long table to find the match. That is not practical for hardware implementation. In the implementation of the *Gigabit Ethernet* circuit, in order to limit the table to a size that could fit into the available space on the FPGA, a 10-bit index is used which restricts the table size to be 1024 entries. A 2-bit network identifier and *Least Significant Byte* (*LSB*) of the 32-bit *IP* address are combined to generate the lookup index. The device supports 3 different networks with network masks of at least 24 bits long. The network identifier is coded as 00, 01 and 10. That allows the host identifier to be at most 8 bits long and thus allows 256 hosts to be in one subnetwork.

The width of the data bus in the RAM is 49 bits. The lower 48-bit word is a MAC address and the 49th bit indicates validation of the the entry. "1" indicates a valid entry and "0" indicates an empty entry. The use of the extra bit simplifies the logic to check the entry validation and enables the software to control the ARP table aging.

2.2.4 Ingress MAC Processing

Figure 2.4 shows the block diagram of the *Ingress MAC* module. The *Ingress MAC* module receives and parses the *MAC* frame from the *GigE ASIC* through a *POS-PHY Level 3* interface. The destination *MAC* address is checked first. If it does not match this card's *MAC* address, the whole *MAC* frame will be passed through the *FPX* without any change. The frame is stored in a *FIFO* temporarily. If the frame

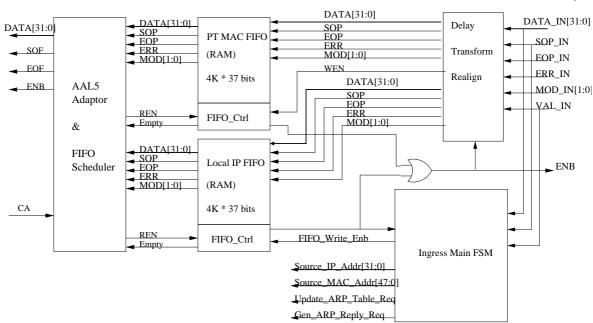


Figure 2.4: Ingress MAC Processing Block Diagram

type is either an ARP request or an ARP reply, the source IP address and the MAC address are fetched and the information is used to update the ARP lookup table. For a matched ARP request, an ARP reply is triggered on the egress side. If the frame has the matched destination MAC address and encapsulates an IP packet (usually this is a control packet), the MAC header is stripped off and the pure IP packet is stored in a FIFO temporarily. All other types of packets will be treated as unknown types and simply discarded.

A scheduler dispatches the pass-through traffic and local traffic to the FPX side in *round-robin* manner. The output IP packet or MAC frame is adapted into an AAL5 frame in order to be fed to the *Frame Wrapper* module. All local IP packets are assigned VCI 50 and all pass-through frames are assigned VCI 51. The *Ingress* MAC module leaves the FCS field of the AAL5 frame blank if the packet or frame is error free; on the contrary, if the packet or frame is marked as an errored one, a nonzero value is filled in the AAL5 FCS field. The Frame Wrapper is responsible for

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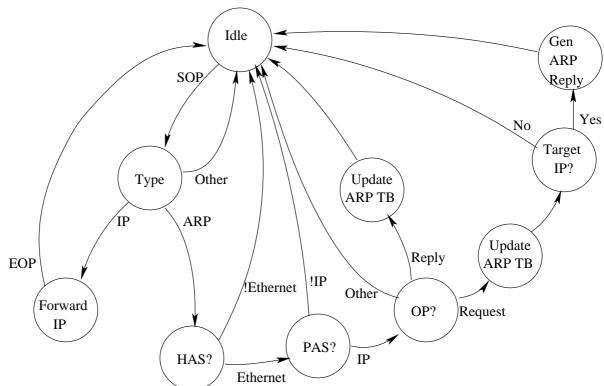


Figure 2.5: Ingress MAC Processing Main FSM

calculating the FCS based on the packet's correctness information. The main *Finite* State Machine (FSM) of the Ingress MAC module is shown in Figure 2.5.

2.2.5 Egress MAC Processing

As shown in Figure 2.6, the *Egress MAC* module receives an *AAL5* frame from the *Frame Wrapper* module. At first all data is buffered in a *FIFO*. This is because the back pressure signal from the *Egress MAC* module can not stop the traffic from the *Frame Wrapper* module immediately and that may cause data to be lost without a buffer. The *FIFO*'s full threshold serves as a back pressure signal to the *Frame Wrapper* module. The threshold must be set to a proper value so that enough room is left for incoming data before the *Frame Wrapper* module responds to this back pressure signal.

20

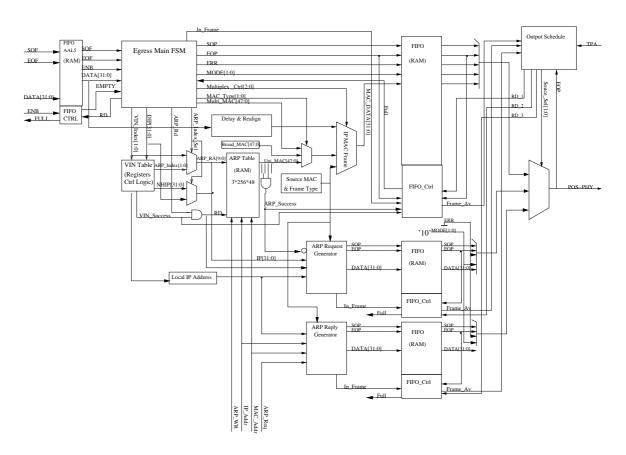


Figure 2.6: Egress MAC Processing Block Diagram

Once the AAL5 frame FIFO is filled with a whole frame or reaches the predefined low threshold, the *Egress MAC* module begins reading data out of the *FIFO*. In the main FSM, the AAL5 frame is classified based on the VCI value. VCI 51 means that a whole MAC frame (i.e. pass-through traffic) is encapsulated in a AAL5frame, so the MAC frame is extracted out and scheduled to be forwarded to the line side. VCI 50 means that the packet is a local IP packet which is generated in the FPX. Under this condition, the FSM must obtain the destination IP address from the AAL5 frame. The IP address might be a broadcast address with format: {Network-Number, -1}. In this case, no ARP lookup is needed. Instead, the Egress MAC module maps the destination MAC address to the broadcasting MAC address FF:FF:FF:FF:FF:FF and forwards the IP packet. If the IP address belongs to a multicast type (i.e. class D address: 0xE0000000 + 28 bit group ID), there is no need to do the ARP table lookup either. The IP address is mapped to the multicast MAC address [19] and forward the packet. In case the IP address is a unicast one, the FSM uses the IP address to generate the index to search the ARP table. If a valid entry is retrieved, the retrieved MAC address is used as the destination MACaddress, thus a whole MAC frame could be assembled to encapsulate the IP packet; if the queried entry is empty or invalid, the *IP* packet is simply discarded and an ARP request frame is generated and scheduled to be sent to the line side network.

With any other VCI value, the AAL5 frame is discarded and an unknown type of frame event is reported to the CCP module. The main FSM is shown in Figure 2.7.

After this processing, any local IP packet with a valid MAC destination address is encapsulated into a MAC frame and then is written into a FIFO. All pass-through MAC frames are written into this FIFO too. Those triggered ARP request frames are written into an ARP Request FIFO. The Egress MAC module also accepts the

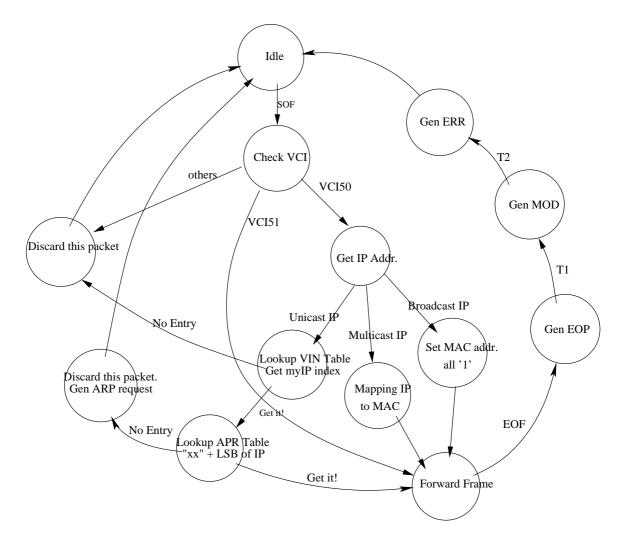


Figure 2.7: Egress MAC Processing Main FSM

requests from the *Ingress MAC* module to generate ARP reply frames and stores them into an ARP Reply FIFO. In a normal working environment, the ARP request and reply happen with low frequency, so the *FIFO* depth is set to 4 frames each.

At last, an output scheduler FSM works in round-robin manner to detect and dispatch data from three FIFOs alternately. If there is a whole frame in the FIFO, the frame is read out and transmitted through a POS-PHY level 3 interface to the GigE Controller ASIC. At this point, all the MAC frames are not padded and the frame CRC is not calculated yet, so actually they are not complete MAC frames. The GigE Controller ASIC is responsible for handling them by correctly configuring the internal registers.

2.2.6 VLAN Support and Route Direction

In order to make the *FPX* system compatible in different application environments, *IEEE 802.1q VLANs* are supported in the *FPX* platform. A jumper on the card must be set before the system operation. For security reason, all local *IP* traffic must use *VLAN ID* 1. The pass-through traffic's *VLAN ID* remains unchanged.

To direct the FPX's routing decision upon receiving cells from the GigE line card or system motherboard, a direction pin should be set through another jumper on the GigE line card. The setting actually controls one bit in the VPI field of the ATM cells which is used to decide where the cell should be forwarded: the Internet side or the Intranet side.

2.2.7 Interface

The FPX system side interface is simple and is described in [6]. The signal SOC indicates the first word of a cell. This word and the following 13 words belong to one

cell. A back-pressure signal is used to control the flow rate when needed. The line side uses a POS-PHY Level 3 standard interface to connect the ASIC PM3386[44]. The POS-PHY Level 3 interface is a 32-bit wide interface with a clock rate of up to 104 MHz (Though we only use 62.5 MHz clock in our system). POS-PHY Level 3 was developed with the cooperation of the SATURN Development Group to cover all applications which bit rates are up to 3.2 Gbit/s. The POS-PHY Level 3 specification [18] defines the requirements for interoperation between devices such as the multi-PHY PM3386 and a single Link Layer device. Each direction within the FPGA logic contains a 4096-byte latency FIFO.

Test and Performance Evaluation 2.3

IOBs

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The GigE logic was synthesized using Synplify Pro and was placed and routed in a Xilinx XC2V1000 FPGA. Table 2.1 summarizes the GigE FPGA place and route results.

Table 2.1: Device Utilization and Timing Summary Block RAMs

SLICEs

4202

Frequency

	61%	77%	82%	82.2 MHz			
Figure 1.1	shows	an envisioned <i>FP</i>	PX system co	onfiguration. I	n order to debug		
the system, all the four cards (2 GigE Line Cards, 1 NID-PT FPX card and 1							
regular FPX car	d) are j	put into a <i>WUG</i>	S as shown	in Figure 2.8.	Two hosts with		
GigE interface co	onnect t	wo $GigE$ cards read	spectively. 4	GLink cards a	are used for other		

line connections. A TCP flow is set up between the two hosts. By this means, we can monitor all internal interfaces by dumping the cells running through them.

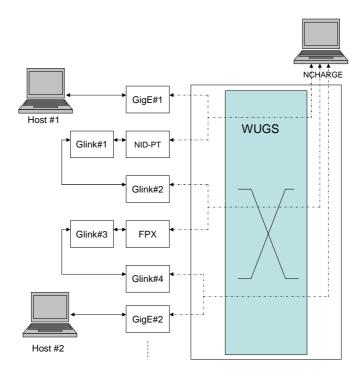


Figure 2.8: FPX System Configuration for Debugging

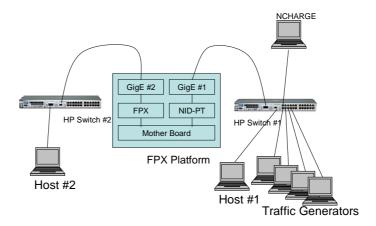


Figure 2.9: FPX System Configuration for Test

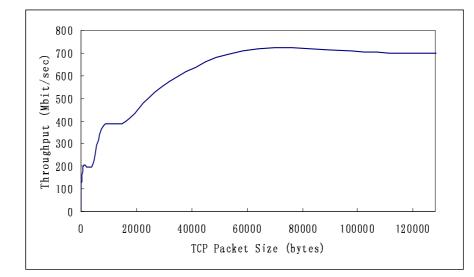


Figure 2.10: A Case of GigE Throughput Test

Once the system passed the test, we set up a standalone FPX system without the WUGS as shown in Figure 2.9. In this configuration, two HP Procurve Switch 2524 [43] are used. Each switch has two GigE ports and 24 10/100M Ethernet ports. On the Intranet side, an NCHARGE sever is running to control and configure the FPX platform. A bunch of hosts can generate and send pass-through traffic to the Internet side.

The host 1's GigE NIC uses a 64-bit/33-MHz PCI bus and host 2's GigE NIC uses a 64-bit/66-MHz PCI bus. To test the system's throughput, WSTTCP [34] is used to transfer data through a TCP flow between the two hosts. Though in theory the PCI bus can inject data at a rate of at least 2 Gigabit/second, due to the software and operating system's limitations, actual throughput is far below that. Figure 2.10 shows the result of one of the experiments we have done. Note that the system only supports 1500-byte MTU.

The experiment shows that with one pair of hosts and one TCP flow, we can get at most 800 Mbit/second throughput. In order to make the system work under a

full gigabit rate, a bunch of hosts with 10/100M Ethernet interfaces should be used to connect with the system through the switch. Each of them sets up a *TCP* connection with the *host 2* so we can easily get an aggregate gigabit throughput.

Chapter 3

Secure Control Packet Processor

To enable secure remote control of a FPX-based firewall, a Secure Control Packet Processor (SCPP) was designed and integrated into the FPX system. Some popular encryption and authentication algorithms were implemented in hardware and could be chosen from as the core components in SCPP.

3.1 Hardware implementation of Security Standard Cores

Confidentiality is achieved by encrypting the control packets before they are sent and decrypting them in the FPX platform. Among many block encryption algorithms, 3DES[41] and AES (*Rijndael*)[31] were implemented because of their efficiency and straightforward hardware implementation.

We also need some form of acknowledgements from the platform to determine the control packet's status. At this point, the authentication of the message is more critical than confidentiality. *HMAC-MD5* and *HMAC-SHA1* were implemented for acknowledgement packet generating.

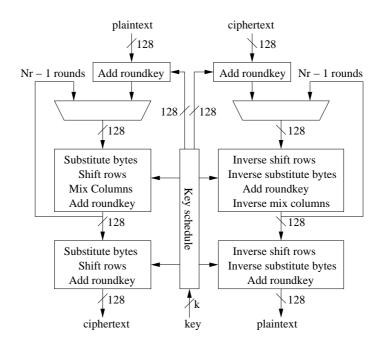


Figure 3.1: AES Algorithm Block Diagram

3.1.1 AES

The *AES* algorithm works by using cryptographic keys of 128, 192 or 256 bits to encrypt 128-bit data blocks. Figure 3.1 describes the AES algorithm. In the figure, kis the number of bits in the key, Nr is the number of iterations (or rounds) performed to complete the encryption or decryption of a single data block. Nr is a function of k and is 10, 12 or 14 for k of 128, 192 or 256 bits, respectively. The key schedule expands the original key to Nr + 1 roundkeys. The operations performed in each round are shown in the figure. Note that the last round for encryption does not include the mix columns step, while decryption is missing the inverse mix columns in its last round.

Although we only require AES decryption for the control packet processor, both encryption and decryption algorithms were implemented. This will make the module more useful in future applications. Figure 3.2 shows the block diagram of the AES implementation. Since the key and the number of rounds are decided at

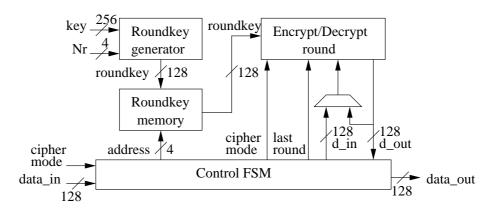


Figure 3.2: AES Hardware Implementation Block Diagram

compile time, a roundkey generator was implemented that computes the roundkeys upon system reset. These keys are stored in the roundkey memory (block RAM) and read as needed. Cipher mode controls the encryption and decryption selection.

AES uses 16 256-byte substitution boxes (Sboxes) for each encryption round and another 16 256-byte inverse Sboxes for each decryption round. If these Sboxes were implemented using registers, each round could be completed in one clock cycle. However, this would consume a great deal of our resources. Instead, we chose to implement these Sboxes as block RAMs. This increased each AES round time to two clock cycles but saved much of the chip resources for other modules. This sacrifice can be made without much concern as it is expected that control packets will arrive sparsely. The EPBC mode is used for data integrity purpose which requires feedback of the previous plaintext block for decryption or ciphertext block for encryption. This eliminates the possibility of using a loop-unrolling implementation of the encryption algorithm. Also, due to our limited FPGA resources, a loop-unrolling implementation makes the design impractical as it would take up most of the FPGA leaving no room for other modules.

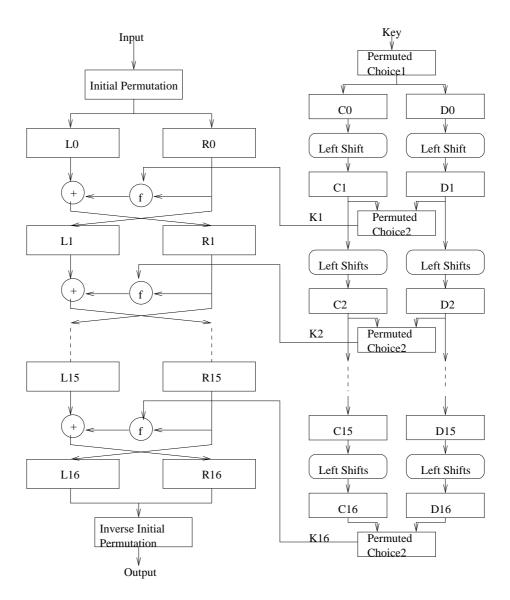


Figure 3.3: DES Implementation Block Diagram

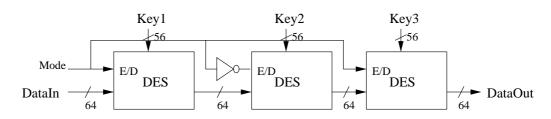


Figure 3.4: 3DES Hardware Implementation Block Diagram

3.1.2 Triple DES

DES is another widely used block encryption algorithm that uses 56-bit keys to encrypt data in 64-bit blocks. Given the vulnerability of DES to a brute-force attack, an alternative approach to get higher security is 3DES. 3DES uses three encryption stages of DES chained together and a unique key for each. The basic DES algorithm is described in Figure 3.3. Figure 3.4 shows the 3DES encryption and decryption structures. A free DES core written in VHDL was found on the web and used to implement our 3DES[15]. It contains both iterative and loop-unrolling versions of the algorithm. Again we chose to use the iterative version for the same reasons discussed in the AES section.

3.1.3 MD5 and SHA-1

MD5 and SHA-1 are message digest algorithms specified for use in *Internet Protocol* Security (*IPSec*). Both algorithms take as input a message of arbitrary length and produce as output a message digest of 128 bits for MD5 and of 160 bits for SHA-1. The input message is first padded and appended with message length to be a multiple of 512 bits. Then the message is processed in 512-bit blocks with an *n*-bit initial value, where *n* is 128 for MD5 and 160 for SHA-1. Further details regarding MD5 and SHA-1 can be found in reference [36] and [13], respectively. The MD5 and SHA-1 cores were implemented using iterative architecture and have a latency of 197

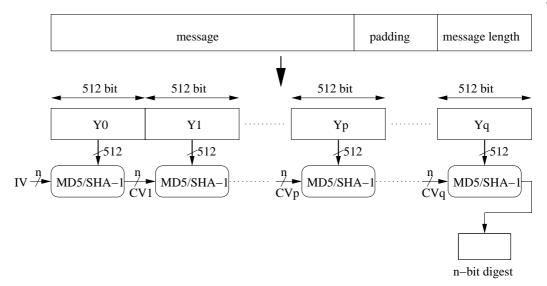


Figure 3.5: MD5 and SHA-1 Algorithm Architecture

and 245 clock cycles respectively to hash a 512-bit data block. These numbers are higher than other implementations of the same algorithms [12]. This is because the four 32-bit additions required by each step of the hashing algorithms were spread out over three clock cycles to increase clock speed. As mentioned earlier, control packets arrive sparsely so latency is not a high concern. The hardware architecture of MD5and SHA-1 is shown in Figure 3.5.

3.1.4 HMAC

HMAC is used in conjunction with either MD5 or SHA-1. It uses a secret key to validate the information being sent from the SCPP back to the administrating host. HMAC can be further described by the following equation:

 $HMAC_{text} = H(K \oplus opad, H(K \oplus ipad, text))$

where K is a secret key (we use a 512-bit key), ipad is the byte 0x36 repeated 64

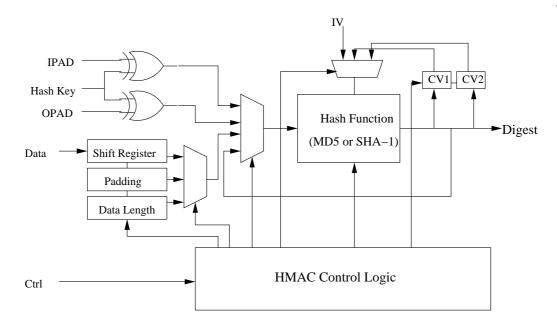


Figure 3.6: HMAC Hardware Implementation Block Diagram

times, opad is the byte 0x5C repeated 64 times, H is hashing function (MD5 or SHA-1). The result is a 128-bit digest for MD5 and a 160-bit digest for SHA-1. Figure 3.6 shows the hardware implementation of HMAC.

We implemented HMAC more efficiently by precomputing $H(K \oplus opad)$ and $H(K \oplus ipad)$ [41]. Because the padded message can fit into one block, this technique doubles the throughput of the circuit by eliminating two of the four hashes that need to be computed for each packet.

3.1.5 EPBC mode

To validate the integrity of control packets after they have been decrypted, AES and 3DES were implemented in *Error-Propagating Block Chaining (EPBC)* mode. We use this mode instead of *HMAC* here because it is nearly free in regard to circuit overhead compared to the hash function. *EPBC* mode allows us to validate the integrity of the decrypted data by comparing the decrypted value of the last block to the predefined *integrity value*. If they are the same, it is reasonable to believe that

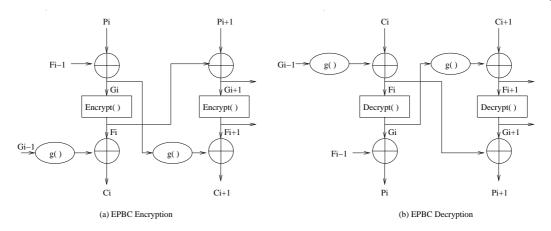


Figure 3.7: EPBC Mode Block Diagram

the control packet has not been tampered with. Otherwise the control packet should be discarded.

As shown in Figure 3.7, EPBC mode can be further described by the following equations where the initial values of F and G are two distinct initial vectors (IVs). The size of the IVs is the same as the block size for each algorithm (128 bits for AESand 64 bits for 3DES). P and C represent the plaintext and ciphertext, respectively. The block number is denoted by i. And finally, E and D represent the encrypt and decrypt functions, respectively.

Encryption:	Decryption:
$G_i = P_i \oplus F_{i-1}$	$F_i = C_i \oplus g(G_{i-1})$
$F_i = E_{key}(G_i)$	$G_i = D_{key}(F_i)$
$C_i = F_i \oplus g(G_{i-1})$	$P_i = G_i \oplus F_{i-1}$

In the above equations, function g() operates as follows:

$$g(G) = \langle G_H + \overline{G}_L, G_H \cdot \overline{G}_L \rangle$$

Where $G \equiv \langle G_H, G_L \rangle$, G_H and G_L are the high and low order halves of G respectively.

3.2 Secure Configuration and Acknowledgement

3.2.1 Configuration Console

A simple protocol was designed to ensure the reliable FPX control and configuration. The control packet is encrypted in the administrating host. For each received control packet, the FPX platform sends back a keyed authenticated acknowledgement packet to report the control packet's status (accepted or dropped). In the following cases, administrating host needs to resend the control packet:

- Timeout;
- Unrecognized acknowledgement packet;
- Acknowledgement packet reports the control packet is dropped.

If administrating host can't correctly configure the FPX platform for several iterations, it might indicate network failure or imply some attack is happening.

3.2.2 Encrypted Control Packet Format

The same control packet format is applied for both *3DES* and *AES* encryptions for uniform processing. The control packet uses 128-bit *IVs* since *AES* requires this. In the *3DES* application, only the first 64 bits of each *IV* are used for decryption and the remaining 64 bits are ignored. We need to pad the control packet body to make it a multiple of the block size. The padding for the control packet is dependent on the encryption algorithm chosen. The last data block in the control packet is an integrity check. This block uses a predefined value that is checked in the hardware when the packet has been completely decrypted. The layout of the control packet is shown in Figure 3.8a.

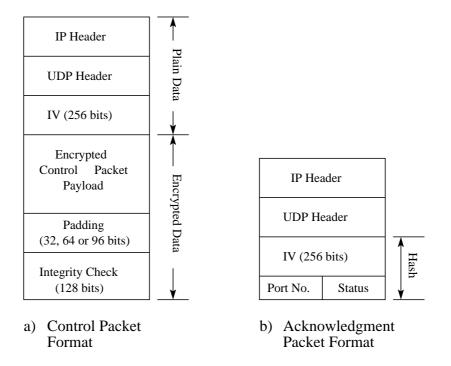


Figure 3.8: Control Packet Formats

3.2.3 Authentication Packet Format

In order to determine if a control packet that was sent to the FPX platform was actually accepted, the FPX platform should return an acknowledgement packet. This packet contains a hash of the IVs concatenated with the 16-bit destination port and a 16-bit status value. Since all IVs are randomly generated, each acknowledgement packet can be identified through its IVs without providing extra information. The layout of the authentication packet is shown in Figure 3.8b.

3.3 Infrastructure

Simply implementing the encryption and hashing algorithms is not nearly enough to provide security features for the FPX platform. Logic was required to identify control packets and pass these packets through SCPP while all other packets pass

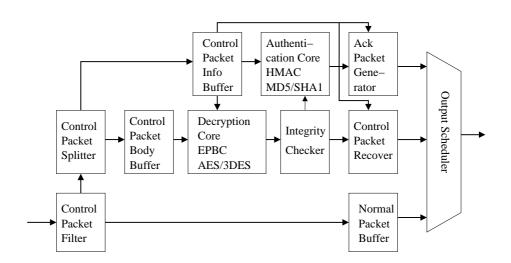


Figure 3.9: Control Packet Processor Architecture

through unmodified. Figure 3.9 illustrates the logic components in the secure control processor. A description of the major components' functionality follows.

Control Packet Filter

This block receives the data from the protocol wrappers and filters out the control packets based on the *FPX* platform's *IP* address and the *UDP* port number. These control packets are sent to the *control packet splitter*. Non-control packets are buffered in the *normal packet buffer* and scheduled to be forwarded to the downstream modules of the *FPX* platform.

Control Packet Splitter

This block further processes the control packets. It extracts the IP addresses, UDP ports and two IVs from the packet and buffers them to be used in the following blocks. Finally, it assembles the encrypted 32-bit words of the packet body into the larger data block necessary for each algorithm (64 bits for *3DES* and 128 bits for *AES*). These data blocks are buffered up to be sent to the *decryption core*.

Control Packet Body and Information Buffer

Due to the decryption latency, *FIFOs* are needed to buffer the data and all necessary information for decrypting, reassembling the control packet and creating authenticated acknowledgement packets.

Decryption Core

The decryption core instantiates either the *AES* or *3DES* core in *EPBC* mode. When the core is not busy, it dequeues a data block from the *control packet body buffer* for decryption. Once a block has been decrypted it is forward to the *integrity checker*.

Integrity Checker

The *integrity checker* is basically a 128-bit comparator. It compares the decrypted value of the last 128-bits of control packets against a predefined integrity check. If any of the cipher blocks was modified prior to decryption, this "error" will propagate to the last decrypted block and it will fail the integrity check. Exact matching means that the packet is the same as the original control packet so it is considered valid. Only valid control packets are forwarded to the downstream modules in the *FPX* platform. Invalid control packets are dropped.

Control Packet Recovery

When a decrypted control packet has successfully passed the integrity check, the recovery component rebuilds the control packet from the decrypted payload using the information previously stored in the *control packet info buffer*.

Authentication Core

The authentication core instantiates either *HMAC-MD5* or *HMAC-SHA1*. For each incoming control packet an authentication digest is computed. The message to be hashed consists of the two *IVs* for the control packet, the destination port, and a 16-bit field indicating the packet status. Once computed, the digest is forwarded to the *acknowledgement packet generator*.

Acknowledgement Packet Generator

For each incoming control packet, an acknowledgement packet is generated. The destination of this packet is simply the source of the corresponding control packet. This information is retrieved from the *control packet info buffer*. A *UDP* packet is then generated using the hash digest as the payload. Once an acknowledgement packet has been generated, the packet generator requests the output bus from the output scheduler.

Normal Packet Buffer

As decrypting control packets is a time consuming process, all other traffic is forwarded around the decryption engine. This buffer receives all normal traffic from the *control packet filter*. Whenever there is an outstanding packet in this buffer it requests the output bus from the output scheduler.

Output Scheduler

This block schedules the output packets in a basic round robin scheme. It services the *control packet recovery*, the *acknowledgement packet generator* and the *normal packet buffer*.

3.4 Results and Analysis

The architecture described has been synthesized using *Synplify Pro* and the *Xilinx* backend place and route tools to implement the design on a *Xilinx Virtex XCV2000E-*6 FPGA. Table 3.1 summarizes the results for the encryption cores, and Table 3.2 summarizes the results for the two authentication cores. The *Rate* column represents the throughput of control packets and acknowledgement packets through the *SCPP*.

From these results we can see that the 3DES core is much more efficient with regards to resource usage. However, throughput of the AES core is several times higher than 3DES. This is primarily due to two factors. The first is the fact that AES decrypts 128-bit blocks at a time, whereas 3DES only decrypts 64-bit blocks. Secondly, 3DES uses many more rounds than AES. With this in mind, it is clear that it would be more beneficial to chose 3DES when space is a major concern. Otherwise, if throughput is a major concern, AES would be more suitable.

Table 3.3 shows the overall system performance of the *FPX* platform which implements a hardware based firewall with different algorithm combinations. *AES*-*128-HMAC-SHA1* gives the highest throughput.

Table 5.1. Synthesis Results. Encryption Cores							
	LUTs		B	lock RAM	Timing	Rate	
	#	%	#	%	MHz	Mbps	
3DES	1223	3%	0	0%	55.2	98	
AES-128	2503	5.8%	44	27%	85.6	547.8	
AES-192	2610	6.0%	44	27%	86.7	462.4	
AES-256	2677	6.2%	44	27%	92	420.6	

Table 3.1: Synthesis Results: Encryption Cores

Table 3.2: Synthesis Results: HMAC Modes

Table 5.2. Synthesis Results. Third Modes							
	L	UTs	Block RAM		Timing	Rate	
mode	#	%	#	%	MHz	Mbps	
MD5	5284	13%	0	0%	58.5	152	
SHA-1	5796	15%	0	0%	56.5	118	

Table 9.9. Theod and Houted Thoward Dobigh								
	Sl	ices	Block RAM		Timing	Rate		
	3DES-HMAC							
config.	#	%	#	%	MHz	Mbps		
MD5	13239	68%	83	51%	49.2	1574		
SHA1	13698	71%	83	51%	50.5	1616		
	AES-128-HMAC							
MD5	13543	70%	123	76%	45.8	1466		
SHA1	14331	74%	123	76%	60.3	1930		
	AES-192-HMAC							
MD5	13775	71%	123	76%	48.8	1560		
SHA1	14102	73%	123	76%	56.6	1811		
AES-256-HMAC								
MD5	13698	71%	123	76%	50.6	1620		
SHA1	14221	74%	123	76%	54.9	1758		

Table 3.3: Placed and Routed Firewall Design

We also compared the hardware implementations' performance with the software benchmarks found in [11]. The benchmark results are based on the C++ code running on an 850 MHz *Celeron* processor. From Figure 3.10, we find that the performance of *3DES* and *AES* is much better than the performance of the software implementation. For hash functions, software implementation is much faster than its hardware equivalent. It makes sense because hash algorithms were designed mainly for software implementation while most of the symmetric encryption algorithms were optimized for hardware implementation.

3.4.1 Software Implementation

While *3DES*, *EPBC* mode and *HMAC* were original code, *AES*, *MD5* and *SHA1* implementations were obtained via the *National Institute of Standards and Technology* (*NIST*)[29].

On each execution, the program randomly generates IVs to be used for encrypting the control packet. The original payload is read from a file, encrypted, and

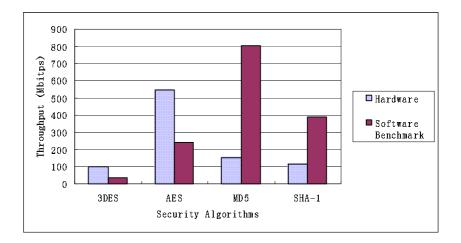


Figure 3.10: Hardware/Software Performance Comparison

appended to the IVs along with the integrity check to make up the encrypted payload for the control packet. At the same time, the selected HMAC algorithm is run on the IVs to create digests for comparison to feedback packets. A digest is created for a feedback packet signifying a successful configuration as well as one signifying a failed configuration (i.e. a dropped control packet).

3.4.2 Testing

Testing of SCPP was performed in a live network using the FPX platform (Figure 3.11) in a WUGS. A modified version of the NCHARGE [40] web interface was used to read our encrypted payloads and create the necessary packet and cell headers. The interface supplies a selection box for choosing both the encryption and the authentication algorithm. It also provides fields for other packet information including IP address, port number and non-encrypted payload data. Once the information for our test packet is entered, the web interface calls a CGI script to interpret the information, run it through the encryption software and send the packet to the hardware via a *Gigabit Link* connector between the PC and WUGS. NCHARGE then attempts



Figure 3.11: FPX Test Platform

to read any acknowledgement packets from the line. Any acknowledgement packet received is displayed and compared to the pre-computed digests. This comparison determines if the control packet was accepted by the FPX or not. If not, the control packet would need to be retransmitted until a successful configuration occurred.

AES-128, AES-192, AES-256, and 3DES with both HMAC-MD5 and HMAC-SHA1 (for a total of eight different core modes) were all tested. Each core passed the tests by successfully configuring the FPX platform and returning expected acknowledgement packets. We also simulated different attacks to the FPX platform, such as fake control packets, message modification and denial of service. All attacks were detected by the FPX platform or the administrating host successfully.

Chapter 4

Secure Remote Control Protocol

4.1 Architecture

Some drawbacks exist in the SCPP structure. First, it is subject to a replay attack. That means an attacker can capture a control packet and send it to the target again at any time. The FPX cannot identify if it is a replay packet. Second, the communication protocol is stop-and-wait. It is too slow if we want to download a large bitfile to the FPX platform. In order to overcome these drawbacks, an improved protocol is presented. It can also be used in any environment in which we need to control a hardware based reconfigurable network node through the public Internet.

The secure configuration architecture provides the infrastructure for secure communications between the control console and *Reconfigurable Hardware Nodes* (RHN) over the Internet. Communications are conducted through encrypted and authenticated control packets. A functional module called the *Secure Control Manager* (SCM) performs all security related tasks, ensuring that only authorized access to the *RHN* is allowed. Figure 4.1 shows the security configuration architecture. A unique aspect of this architecture is that *SCM* is implemented in pure hardware.

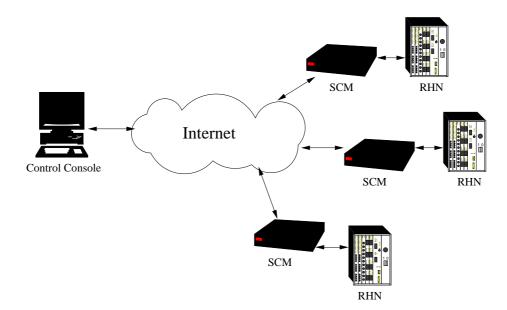


Figure 4.1: Secure Configuration Architecture

Avoiding software involvement in network processing is important because it prevents the nodes from being hacked using traditional vulnerabilities found in operating systems. *SCM* implements some encryption and authentication algorithms to guarantee data confidentiality and integrity. It is also responsible for establishment, maintenance and termination of the secure connection.

4.2 Protocol

A security protocol is needed to secure the communications between the control console and RHNs. The goal of this protocol is to provide a secure communication channel, so that attackers will not be able to damage or steal information from the RHNs. Even if the node is under attack or experiencing network failure, the protocol can let the control console be aware of the attack and take actions. The protocol includes a flow control and an error control scheme. It relies on positive acknowledgement and retransmission when the control console does not receive an acknowledgement within a given timeout period. The protocol need to be implemented not only on the administration host in software, but also on the SCM in pure hardware which is hard to accommodate a complicated protocol. Fortunately, in most cases, the control console and the RHN act as master and slave. Control console is always take the initiative to establishment and termination of connections. This feature enables us to design a simple yet efficient protocol based on Go-back-N ARQ to support only end-to-end communication, with which at the same time configuration packets are issued only from one control console.

A sliding window mechanism is used to provide flow control. Similar to the mechanism in HDLC, an acknowledgement (ACK) of new incoming packets automatically moves the sliding window to grant permission to more packets. In our system, the size of the sliding window is decided mainly by the buffer size in the SCM. Error control is done by exerting encryption and authentication on each control packet. Retransmission of a packet is necessitated when a packet never arrives at the reconfigurable hardware node or an arriving packet is discarded by the RHN because of errors. Here we implement a batch retransmission strategy, particularly because of the requirement that the packets configure or reprogram the hardware nodes in an in-order fashion. It works by maintaining one retransmission timer for the entire sliding window. If no ACK is received before the timer expires, the control console must retransmit from the first packet and reset the timer; otherwise, the sliding window is adjusted and the timer is reset. A sequence number indicating the order of control packet is encrypted in the packet body. For each establishment of a new connection, a random sequence number is generated in the RHN and sent back to the control console. The sequence number is incremented during the maintenance of the connection.

Handling connection termination can be complicated in some protocols. However since only end-to-end communication is supported and the SCM does not preserve any information for the current connection except for the sequence number, the termination of the current connection is only meaningful for the control console. In this protocol, connection termination to the RHN is simply establishment of a new connection. As to the control console, an initiative termination is stopping sending new control packet after the ACK of the last control packet; and a passive termination is unsuccessful communication with a timeout period. In the second case, the control console will be aware of either the network failure or potential attacks to the system.

During the above discussion, we assume that before each connection the control console and the RHN shares a secret key, which is used to protect all transferred data. Security key management is extremely difficult for pure hardware implementation. Therefore, in our current protocol, we assume the secret key is hardcoded in the RHN and shared with each control console.

This protocol is strong enough to protect the configurable hardware nodes from the common attacks, which we talked about in the section one. First, eavesdropping and fake packet attacks are avoided by applying encryption and authentication to the control packets. Second, replay attack is prevented by using encrypted sequence number. By randomly generating sequence number SN from the control console side, even if malicious users capture all the packets sending from the host, re-sending them to the RHN will not be accepted due to the discontinuity of the sequence number. The administration host has a time-out mechanism, therefore, when RHN is under attack or network fails, the host can be aware of these problems and take action.

The communication between the administration host and the RHN is through UDP packets. We call it control packet. For uniform processing, all control packets

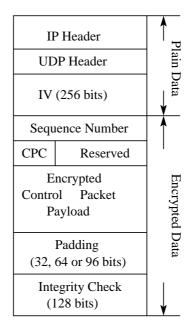


Figure 4.2: Secure Control Packet Format

have the same format. Control packets include session establishment packet, configuration packet, status inquiry packet, and acknowledgement packet. The destination IP address and UDP port number are used to identify the individual configurable module inside the *RHN*.

The first 4 32-bit words in the UDP payload is IVs required by EPBC mode. The next word is 32-bit SN for flow control. The first byte of the following word denote a unique *Control Packet Code* (*CPC*) for each type of the control packet. The administration host and the *RHN* can distinguish and process the packet by its *CPC*. All *RHN* control or configuration information follows. Control packet payload is padded to be multiple of the block size. The last 128-bit data block in the control packet is integrity check. This block uses a predefined value that is checked in the hardware when the packet has been completely decrypted. The layout of the control packet can be seen in Figure 4.2. Communication is divided into two phases: the session establishment phase and configuration phase. To establish a communication session, the host sends a control packet with CPC equal to 0 during session establishment phase. Once the RHN receives and accepts the connection requirement, an acknowledgement control packet is sent back with CPC equal to 0. A randomly generated SN telling the administration host to start sending packets from the appointed SN is also encrypted in the acknowledgement packet body. If the administration host doesn't receive the ACK within a timeout period, it sends the initialization control packet again. If this fails after a predefined number of times, the administration host gets the ACKsuccessfully, the communication goes into the configuration phase.

The administration host sends configuration packet (CPC = 1) or status request packet (CPC = 2) with successive SN within the bound of the current sliding window. The RHN receives a error-free packet, it sends back an ACK (CPC = 1) to tell the host the next expected SN N'. The effect of this ACK actually acknowledges all packets with SN prior to this one N'. If the SN of this error-free packet matches the expected SN, RHN will forward this packet to the rest of the RHN modules. If due to any error the RHN can not accept the current control packet, it silently discard the packet and whatever the following control packets till an acceptable one with the expected SN. If the host experiences a timeout without receiving any ACK, it will resend all the packets in the current window. On condition that RHN accepts a status inquiry packet, it sends back an ACK with the inquired information assembled in the packet body and CPC set to 2. This indicates it is not only an acknowledgement, but also a reply to an inquiry.

4.3 Application in FPX system

Considering the reality of the FPX system, we decided to apply the encryption in the NID-PT card and leave the data integrity and sequence number control logic to be processed in the regular FPX card. AES is exerted only to the control cell payload. Firstly, this arrangement conforms to the principle of layered protocol. Mapped into the seven layer network model, encryption functions could be in physical layer while data integrity and authentication check functions could be in link layer. Secondly, current FPX system and related software are all well defined and work well. The control cell's format inherited the data integrity check by AAL0 CRC and sequence number control by SN field. What's more, the length of the cell payload is 48 bytes, that are exactly 3 128-bit blocks for AES cipher. There is no important information that needs to hide in cell header so we don't need to encrypt it at all. All these considerations simplified the modifications and new designs that need to be added to the FPX system. The logic view of the NID-PT FPX card is shown in Figure 4.3

The NID FPGA on the NID-PT card has consumed more than 75% of the resource. The encryption and decryption module have to be placed in the RAD FPGA. Only control cells need to be routed to the RAD. Two modules shown in Figure 4.4 are used in RAD to process bidirectional control cells.

The incoming cell is splitted into two parts: the header and the payload. The cell header is stored in a *FIFO* and the cell payload is transformed to 3 128-bit data blocks to be buffered in another *FIFO*. An *AES* core retrieves the data block from the payload buffer to encrypt or decrypted it. After each 3 consecutive data blocks are processed, one cell header is read out from the header buffer and a whole *ATM* cell is reassembled and sent back to *NID-PT*. A back pressure signal is used to control the flow rate.

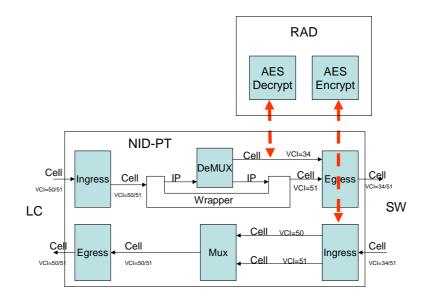


Figure 4.3: NID-PT FPX overview

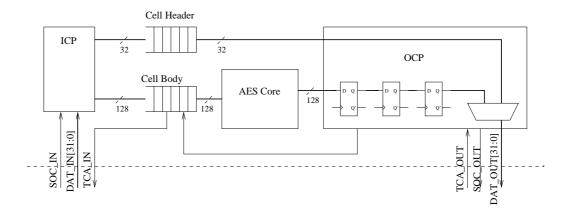


Figure 4.4: RAD AES Module Block Diagram

By restricting the key size to 128 bits, *AES* core need at least 11 clock cycles to process one 128-bit data block. The system will work under 62.5 MHz frequency, so roughly we can get the control cell throughput up to 727 Mbps.

Chapter 5

Conclusion

5.1 Remarks

The FPX platform can be applied in many network processing systems such as firewalls, packet classifiers, content scanners and copyright protection units.

A GigE Card FPGA was designed to provide a line interface for the FPX platform. The FPGA implements ARP and transforms packets between ATM and Gigabit Ethernet. The card is fully tested and can support 1 Gbit/sec throughput.

The GigE card FPGA implements ARP, but it is not fully compliant with the standard in that the ARP table does not support entry aging. That feature is expensive to implement in hardware. We can implement it in software by periodically polling the table entries. However, in the current FPX platform applications, this is not a critical requirement.

For historical reason, the basic unit processed in FPX is an ATM cell. It is not necessary in some of the FPX applications and it does introduce extra overhead. The evolving system will get rid of this step by step. We also made efforts to solve the security problem when configuring the FPX platform through the public Internet. A suite of security algorithms were implemented in hardware and they were applied in SCPP to provide baseline protection to the control and configuration channel of the FPX platform.

Though the SCPP architecture provides strong protection to the FPX platform configuration channel, it is cumbersome and not very efficiency. The main achievement is we implemented a suite of hardware cores and verified them in real applications. They are the base blocks to build the future hardware based network security applications. Another problem is the SCCP can lack of defense against the replay attacks, so we proposed a more robust and more general protocol which intends to secure the control and configuration channel between central console and the hardware based network nodes. A practical module was designed to support this protocol in the FPX platform.

5.2 Future Work

As the network bandwidth continues growing explosively, the FPX platform may be applied in different and higher bandwidth environments, such as $SONET \ OC-192$ and 10 Gigabit Ethernet. More types of Network Interface Card (NIC) will be required. Still, logic are needed to provide the bridge between the line side and the system side. For robust application and fault tolerance, the system should support Automatical Protection Switch (APS). A backup FPX platform can provide protection when network failure occurs without interrupting the whole system.

For secure control and configuration, if we consider the scalability issue, it is actually a secure and reliable multicast problem. There already exist a lot of protocols and algorithms that try to solve this problem but no one is widely accepted and deployed. This is still an open area for future research. The multicast model is source-specified, the problems include many aspects such as source authentication, access control, key distribution and network topology. The main constraint in our system is the limited hardware resource.

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