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A Next Generation Electronic Commerce Server

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WUCS-99-02
January 28, 1999
eMediator: a Next Generation Electronic Commerce Server

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*This material is based upon work supported by the National Science Foundation under CAREER Award IRI-9703122, Grant IRI-9610122, and Grant IIS-9800694.
¹To license eMediator for academic or commercial use, please contact the author.
1 Introduction

Electronic commerce is taking off rapidly, but the full power of AI, algorithmic support, and game theoretic tools has not been harnessed to improve its efficiency. This paper presents eMediator, a next generation electronic commerce server that demonstrates some ways in which these techniques can improve ecommerce both in terms of processes and outcomes. The result of our 2-year implementation effort is now available for use on the web at http://ecommerce.cs.wustl.edu/emediator/. Three components of eMediator are discussed: an auction house, a leveled commitment contract optimizer, and a safe exchange planner. Each one exhibits interesting interplay between algorithms and game theoretic incentive engineering.

2 eAuctionHouse

Several successful commercial Internet auction sites exist—such as eBay and OnSale—and interesting academic auction houses have recently appeared on the Internet [Wurman et al., 1998, Rodriguez-Aguilar et al., 1997]. Our motivation in developing an auction server was to prototype novel next generation features, and test their feasibility both computationally and in terms of user comfort. One of the services that eMediator provides is a free-to-use Internet auction prototype called eAuctionHouse. It allows users from across the Internet to buy, sell, and set up auctions. It is a third party site, so both sellers and buyers can trust that it executes the auction protocols as stated. It is implemented in Java, with some of the compute-intensive matching algorithms in C++. The information about the auctions is stored in a relational database to increase reliability. To our knowledge, our server is the first—and currently only—Internet auction that supports combinatorial auctions, bidding via graphically drawn price-quantity graphs, and by mobile agents. It also offers a wide range of auction types to be chosen from, and supports the user in that choice. These features are now discussed in order.

2.1 Combinatorial auctions

In a sequential auction, items are auctioned one at a time. If a bidder has preferences over bundles, i.e. combinations of items (as is often the case
e.g. in electricity markets, equities trading, bandwidth auctions [McAfee and McMillan, 1996, McMillan, 1994], and transportation exchanges [Sandholm, 1993]), then bidding in such auctions is difficult. To determine her valuation for an item, the bidder needs to guess what items she will receive in later auctions. This requires speculation on what the others will bid in the future because that affects what items she will receive. Furthermore, what the others bid in the future depends on what they believe others will bid, etc. This counterspeculation introduces computational cost and other wasteful overhead. Moreover, in auctions with a reasonable number of items, such lookahead in the game tree is intractable, and then there is no known way to bid rationally. Bidding rationally would involve optimally trading off the cost of lookahead against the gains it provides, but that would again depend on how others strike that tradeoff. Furthermore, even if lookahead were computationally manageable, usually uncertainty remains about the others' bids because agents do not have exact information about each other. This often leads to inefficient allocations where bidders fail to get the combinations they want and get ones they do not.

In a parallel auction the items are open for auction simultaneously and bidders may place their bids during a certain time period. This has the advantage that the others' bids partially signal to the bidder what the others' bids will end up being for the different items, so the uncertainty and the need for lookahead is not as drastic as in a sequential auction. However, the same problems prevail as in sequential auctions, albeit in a mitigated form.

Combinatorial auctions can be used to overcome the need for lookahead and the inefficiencies that stem from the uncertainties [Rassenti et al., 1982, Sandholm, 1993, Rothkopf et al., 1998]. In a combinatorial auction bidders may place bids on combinations of items. This allows the bidders to express complementarities between items instead of having to speculate into an item's valuation the impact of possibly getting other, complementary items. This capability is particularly important in illiquid, highly volatile, or non-commoditized markets where it is unsure whether one can acquire the items of a desired bundle one at a time. Our auction server supports a variety of combinatorial auctions. The following subsections discuss some of them.
2.1.1 OR-bids

In the combinatorial auction setting that has been most commonly discussed [Rothkopf et al., 1998], each bidder can bid on combinations of indivisible items, and her bids are joined with non-exclusive OR, meaning that any number of her bids can be accepted. While combinatorial auctions have the desirable features that they can avoid the need for lookahead by the bidders and tend to therefore lead to more efficient allocations, they impose significant complexity on the auctioneer because the auctioneer needs to determine the winners. This is a nontrivial task. For example, the Federal Communications Commission saw the desirability of combinatorial bidding in their bandwidth auctions, but it was not allowed due to perceived intractability of winner determination.

Formally, winner determination with OR-bids is the problem of deciding which bids win so as to maximize the sum of the bid prices, under the constraint that every item is allocated to at most one bid. This cannot be done in general in polynomial time in the number, \( n \), of bids received, unless \( \mathcal{P} = \mathcal{NP} \):

**Proposition 2.1** Winner determination is \( \mathcal{NP} \)-complete.

**Proof.** Winner determination is weighted set packing, and set packing is \( \mathcal{NP} \)-complete [Karp, 1972]. \( \square \)

Even approximate winner determination is hard if one is interested in worst case guarantees:

**Proposition 2.2** No polytime algorithm can guarantee an allocation within a bound \( \frac{1}{n^{1-\epsilon}} \) from optimum for any \( \epsilon > 0 \) (unless \( \mathcal{NP} \) equals probabilistic polytime).

The proof is based on [Håstad, 1999], and we present it in [Sandholm, 1999].

If the bids exhibit special structure, better approximations can be achieved in polynomial time [Chandra and Halldórsson, 1999, Halldórsson, 1998, Hochbaum, 1983, Halldórsson and Lau, 1997], but even these guarantees are so far from optimum that they are irrelevant for auctions in practice [Sandholm, 1999].

Polynomial time winner determination can be achieved by restricting the combinations on which the agents are allowed to bid [Rothkopf et al., 1998]. However, because the agents may then not be able to bid on the combinations
they want, similar economic inefficiencies prevail as in the non-combinatorial auctions.

We recently generated another approach to optimal winner determination. The motivation was to

- allow bidding on all combinations.
- strive for the optimal allocation.
- capitalize heavily on the sparseness of bids. In practice the space of bids is necessarily extremely sparsely populated. For example, if there are 100 items, there are $2^{100} - 1$ combinations, and it would take longer than the life of the universe to bid on all of them even if every person in the world submitted a bid per second. Sparseness of bids implies sparseness of the allocations $\mathcal{X}$ that need to be checked. Our algorithm constructively checks each allocation $\mathcal{X}$ that has positive value exactly once, and does not construct the other allocations. Therefore, the algorithm only generates those parts of the search space which are actually populated by bids. The disadvantage then is that the run time depends on the bids received.

We achieve these goals by a tree search algorithm that capitalizes heavily on the fact that the space of bids is necessarily sparsely populated in practice. We do this via provably sufficient selective generation of children in the search and by using a method for fast child generation, heuristics that are accurate and optimized for speed, and four methods for preprocessing the search space. A paper discussing the algorithm in detail has been submitted for review elsewhere.

2.1.2 XOR-bids

The above methods for conquering the intractability of winner determination are based on the common assumption that the bids are superadditive: $b(S \cup S') \geq b(S) + b(S')$. But what would happen if agent 1 bid $b_1(\{1\}) = 5$, $b_1(\{2\}) = 4$, and $b_1(\{1, 2\}) = 7$, and there were no other bidders? The auctioneer could allocate items 1 and 2 to agent 1 separately, and that agent’s bid for the combination would value at $5 + 4 = 9$ instead of 7. So, the current techniques focus on situations where combinational bids are introduced to
capture synergies (positive complementarities) among items. On the other hand, in many real world settings local subadditivities can occur as well. For example, when bidding for a landing slot for a plane, the bidder is willing to take any one of a host of slots, but does not want more than one.

To address this, in eAuctionHouse, the bidders can submit XOR-bids, i.e. bids on combinations such that only one of the combinations can get accepted. This allows the bidders to express general preferences with both positive and negative complementarities. Our current work focuses on developing optimal winner determination algorithms for this more general setting. Naturally this problem is even harder than the basic winner determination problem because the latter is a special case of the former. Therefore, the negative results, \( \mathcal{NP} \)-completeness and inapproximability, apply to this setting as well. Our current winner determination algorithm for this setting is fast, but does not guarantee optimality.

To allow an efficient allocation to be reached, it would be desirable to extract truthful valuation revelations as the bids to the auctioneer. Bidding truthfully can be made incentive compatible (a dominant strategy) by using the Groves-Clarke mechanism [Groves, 1973, Clarke, 1971]. This means that each bidder is motivated to bid truthfully irrespective of what the others bid. This renders counterspeculation unnecessary. The Groves-Clarke mechanism can be applied to the combinatorial auction setting as follows. Winning bids are determined so as to maximize the auctioneer’s revenue under the constraint that each item can be allocated to at most one bid. The amount that an agent needs to pay is the sum of the others’ winning bids had the agent not submitted any bids, minus the sum of the others’ winning bids in the actual optimal allocation. Therefore, the winner determination problem has to be solved once overall, and once per winning agent without any of that agent’s bids. This makes fast winner determination even more crucial. Note that for example just removing one winning bid at a time would not constitute an incentive compatible mechanism. Incentive compatibility can also be lost if either winner determination or price determination is done only approximately.

2.1.3 OR-XOR-bids

In addition to the tractability of winner determination, the convenience of using combinatorial auctions is another important issue. While XOR-bids
allow the bidder to express general preferences, in the worst case this would involve placing a bid for each of the $2^m - 1$ possible combinations, where $m$ is the number of items. A shorter representation of preferences without loss of expressive power could be possible by allowing a richer input language. One idea toward this direction was presented early on by Rassenti et al. [Rassenti et al., 1982]. They allowed the bidder to place combinational bids and to state the maximal number of combinations that could be accepted. An XOR-bid is a special case of this where that number is one. In our auction server, we allow the user to submit multiple XOR-bids. We do this in table form, where each row is a combinational bid, and the rows are combined with XOR, see Figure 1. These multiple bids are combined together with a non-exclusive OR. We do this by allowing the user to submit multiple tables. This method maintains full expressive capability, but we believe that it is a more natural way to input preferences, and that it will lead to shorter input descriptions than XOR-bids only. Other enrichments to the language are also be possible. Since even basic XOR-bids have full expressive power, expressiveness should be viewed as a necessary but not sufficient condition. Between fully expressive input languages the appropriate comparison criterion is the convenience of their use in the particular application domain in question.

2.1.4 Other generalizations of combinatorial auctions

Our input representation, Figure 1, also allows combinatorial double auctions instead of just single-sided auctions. In other words, there can be multiple buyers and multiple sellers. In addition to double auction extensions, it allows combinatorial auctions where the agents can bid for multiple units of each item in a combination (the number of units is specified in each cell of the table). The latter splits into two cases depending on whether the matches of units have to be exact or whether partial matches are allowed. Currently while we are developing optimal matching algorithms for these more general combinatorial auctions, we use approximate matching algorithms in our server.

2.2 Bidding via price-quantity graphs

Price-quantity graphs are supported so that bidders can express continuous preferences, see Figure 2. For example when a bidder buys a larger quantity,
Bid in Electricity auction (19980723192509)

Bid name (optional)

Electricity for refinery

Bid type

XOR bid

Bid expired:

- good until fulfilled or canceled.
- in [ ] days [ ] hours [ ] minutes.
- at 0000 [date], [hour] [minute] EST.

Within each row of the following table, you are bidding for a combination of items. Different rows represent alternative combinations which are XORed together; at most one of them will be fulfilled. Negative numbers mean you want to sell. Both selling and buying can exist in the same row.

<table>
<thead>
<tr>
<th>No</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Name/Unit</th>
<th>Price ($ in)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-2692</td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-2515</td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>-2470</td>
</tr>
</tbody>
</table>

Figure 1: A combinatorial XOR-bid in our auction server. The example is from an electricity market scenario where the agents can bid for combinations of electricity for different hours of the day, and for multiple Mega Watt hours for each hour of the day. In this example, a refinery operator needs three consecutive hours of electricity for her plant. She prefers to start at 8 am because that is a more suitable time and running the plant at that time requires less electricity. However, starting at 6 am or 7 am is also feasible.

she might only accept a lower unit price. Naturally, a bidder accepts anything below the curve as well (automatically colored region) because she will get the same quantity as on the curve, but at a lower price. Similarly, a seller would accept anything above her curve.
Figure 2: A price-quantity graph allows the user to express continuous preferences in the auction server of eMediator. This figure corresponds to the user being able to hold a video-conference at three alternative picture resolutions requiring a bandwidth of 15, 60, or 120 Mbps. The auctioned item could be a prebundled combination of items. For example, the virtual circuit from LA to Prague can use several network links owned by different backbone providers.
In the implementation, the curves are piecewise linear both for drawing convenience and for the convenience of winner determination. In single sided auctions with price-quantity graph bidding, the winner determination algorithm works as follows. It sums the demand for every unit price (it does not loop through prices but uses the endpoints of each linear piece of the curve to do this). Then, it picks the aggregate solution that maximizes the unit price under the constraint that not more is demanded than is available. Each bidder then gets the amount that she bid at that unit price. In double auctions, both supply and demand curves are separately aggregated, and any one of the points were supply meets demand is chosen. If the curves were noncontinuous, it is possible that no match exists. This holds both for single and double auctions. To prevent this, we use continuous curves, i.e. the slope of each linear segment is finite. We do not assume that the curves are monotonic, see e.g. Figure 2.

2.3 Support for choosing an auction type

The auction server supports a wide variety of auction types. The user that sets up a given auction (she may be a buyer, a seller, or a third party facilitator) decides the auction type. However, since the space of different auction types is enormous, the auction server helps the user in making the choice. First, only choices that are sensible based on game theoretic analyses or economics experiments are provided as alternatives. Furthermore, there is an expert system that restricts the choice of auction types given the auction setting, see Figure 3. For any given auction setting, it tells the user what kinds of bids can be accepted, and what price determination schemes should be used. The auction setting differs based on whether it is a single or double auction, whether there is one or multiple items, and whether there is one or multiple units of each item. Furthermore, the units can be divisible or indivisible. The bid types include a regular price bid where the user specifies the price for a good; a price-quantity graph bid as in Figure 2; an OR-bid; or an OR-XOR-bid.

The first-price pricing scheme charges the buyer the price of her bid. This scheme leads to underbidding. In single unit ascending open-cry auctions, each bidder's dominant strategy is to bid a small increment more than the current price, and stop when her valuation is reached. In sealed-bid auctions with common knowledge assumption about the priors from which the bidders’
private valuations are drawn, a Nash equilibrium analysis can be conducted to determine how much each agent should underbid as a function of her valuation.

The second-price (Vickrey) auction charges the winning bidder the price of the second highest bid. Under certain restrictions [Sandholm, 1996], it is each bidder’s dominant strategy to bid her true valuation [Vickrey, 1961].

The multi-unit Vickrey auction is a generalization of the Vickrey auction to settings with multiple units of an item, or in other words, multiple indistinguishable goods. Each bidder can submit multiple bids. The units are assigned from highest bid downward until they run out. Each winning bid is charged the price of the bid that it displaces from the set of winning bids. This achieves incentive compatibility, i.e. each bidder is motivated to bid truthfully, independent of what others bid. Another possible generalization of the Vickrey auction for this setting is to charge every bidder the price of the highest bid that just did not win. Our auction server uses the former method because the latter is not incentive compatible: it falls prey to demand reduction lies by the bidders [Ausubel and Crampton, 1996].

For multi-item auctions (with one or more units per item), the Groves-Clarke mechanism, discussed earlier, is the appropriate generalization of the Vickrey auction. Each bidder’s dominant strategy is to bid truthfully.
In double auctions, our server splits the gains equally in the standard way. The price is half way between the bid and the ask.

The auctions in *eAuctionHouse* also have several other parameter, including:

- Whether or not matches have to be exact in multi-unit auctions.
- Tie-breaking rule: random, older bid overrides, or newer bid overrides.
- When to clear the auction: when a specific time is reached, every time a bid is received, periodically, or when no bids have been received for a specified time.
- When the auction permanently closes: when it is cleared, when no bids have been received for a specified time, or when the auction’s owner cancels it.
- Whether or not bid retraction is allowed (possibly for a penalty) before winners are determined.
- Whether or not bid retraction is allowed (possibly for a penalty) after winners are determined.
- What information is revealed to the bidders during bidding: all bids, highest bids, or none.
- What information is revealed to the bidders after clearing: all bids, winning bids, or none.

### 2.4 NOMAD: Mobile agents as auction participants

Our auction house supports mobile agents so that a user can have her agent actively participating in the auction while she is disconnected. For example, the user can launch her agent over the phone from an airplane using a laptop, and then disconnect. Mobile agents that execute on the agent dock which is on (or near) the host machine of the auction server also reduce the network latency—an issue of key importance in time-critical bidding. The Michigan Internet AuctionBot [Wurman *et al.*, 1998] provides a TCP/IP-level message protocol via which agents could participate in their auction.
Their auction server differs from ours in that they do not provide support for mobile agents. Our auction server uses the commercial Concordia agent dock from Mitsubishi to provide mobile agents a safe execution platform from where they can observe what is transpiring in the auctions, bid, set up auctions, move to other hosts, etc. The user has the full flexibility of Java programming at her disposal when designing her mobile agent. We also provide an easy-to-use HTML interface for non-programmers where the user can specify what she wants her agent to do, and our system automatically generates the Java code for the corresponding mobile agent, and launches it. The following mobile agents are currently available:

1. The information agent goes to an auction and sends email to the user when specified events occur. Using this agent, the user does not have to poll the auction, but gets notified of important events immediately.

2. The incrementor agent implements the dominant strategy on the user's behalf in single-item single-unit ascending open-cry first-price private value auctions. It bids a small increment more than the current highest price, and stops if the user's reservation price is reached. With this agent the user does not have to follow the auction, and her dominant strategy in these settings is to report her valuation truthfully to the agent.

3. The N-agent underbids optimally on the user's behalf in single-item single-unit sealed-bid first-price auctions where the number of bidders, N, is known, and the bidders' private valuations are independently drawn from a uniform distribution. Specifically, the symmetric Nash equilibrium strategy is to bid the user's valuation times $\frac{N-1}{N}$ [Rasmusen, 1989]. The user is then motivated to reveal her true valuation to the agent.

4. The control agent goes to an auction and submits very low noncompetitive bids. It is a speculator's tool to artificially increase the number, N, of bidders in an auction to mislead others, e.g. the N-agent. For example, it is in the seller's interest to submit control agents so that N-agents would bid higher.

5. The discover agent computes the expected gain from bidding a small amount more than the current highest price according to the agent's
current distribution of her valuation. This is intended for settings where
the user does not know her exact valuation for the item, but only a
probability distribution on it. In the future, the probability distribution
could be updated by new events, or in non-private value auctions, by
what others have bid.

Unlike current electronic commerce servers which usually only provide
an auction house, eMediator provides other types of services for facilitating
ecommerce in addition, such as a leveled commitment contract optimizer, and
a safe exchange planner. These are discussed in Sections 3 and 4 respectively.

3 Leveled commitment contract optimizer

eMediator includes an optimizer for leveled commitment contracts. Normal
full commitment contracts are unable to take advantage of the possibilities
that such future events provide. Once an agent agrees to a contract, she has
to follow through no matter how future events unravel. Although a contract
may be profitable to an agent when viewed _ex ante_, it need not be profitable
when viewed after some future events have occurred, i.e. _ex post_. Similarly, a
contract may have too low expected payoff _ex ante_, but in some realizations
of the future events, it may be desirable.

_Contingency contracts_ have been suggested for utilizing the potential pro-
vided by future events among self-interested agents [Raiffa, 1982]. The con-
tact obligations are made contingent on future events. In some games this
increases the expected payoff to both parties compared to any full com-
mmitment contract. However, contingency contracts are often impractical because
the space of combinations of future events may be large and unknown. Also,
when events are not mutually observable, the observing agent can lie about
what transpired.

_Leveled commitment contracts_ are another method for capitalizing on fu-
ture events [Sandholm and Lesser, 1996]. Instead of conditioning the contract
on future events, a mechanism is built into the contract that allows unilat-
eral decommitting. This is achieved by specifying in the contract the level
of commitment by decommitment penalties, one for each agent. If an agent
wants to decommit—i.e. to be freed from the obligations of the contract—it
can do so simply by paying the decommitment penalty to the other party.
The method requires no explicit conditioning on future events: each agent
can do her own conditioning dynamically. No event verification mechanism against lying is required either. The decommitment possibility increases each agent's expected payoff under very general assumptions.

We analyze contracting situations from the perspective of two risk neutral agents each of which attempts to maximize his own expected payoff: the contractor who pays to get a task done, and the contractee who gets paid for handling the task. Handling a task can mean taking on any types of constraints. The method is not specific to classical task allocation. The contractor tries to minimize the contract price \( \rho \) that he has to pay. The contractee tries to maximize the payoff \( \rho \) that she receives. We study a setting where the future of the agents involves uncertainty. Specifically, the agents might receive outside offers.\(^2\) The contractor's best outside offer \( \bar{a} \) is only probabilistically known \textit{ex ante} by both agents, and is characterized by a probability density function \( f(\bar{a}) \). If the contractor does not receive an outside offer, \( \bar{a} \) corresponds to its best outstanding outside offer or its fall-back payoff, i.e. payoff that it receives if no contract is made. The contractee's best outside offer \( \bar{b} \) is also only probabilistically known \textit{ex ante}, and is characterized by a probability density function \( g(\bar{b}) \). If the contractee does not receive an outside offer, \( \bar{b} \) corresponds to its best outstanding outside offer or its fall-back payoff.\(^3\) The variables \( \bar{a} \) and \( \bar{b} \) are assumed statistically independent.

The contractor's options are either to make a contract with the contractee or to wait for \( \bar{a} \). Similarly, the contractee's options are either to make a contract with the contractor or to wait for \( \bar{b} \). The two agents could make a full commitment contract at some price. Alternatively, they can make a leveled commitment contract which is specified by the contract price, \( \rho \), the contractor's decommitment penalty, \( a \), and the contractee's decommitment penalty, \( b \). We restrict our attention to contracts where \( a \geq 0 \) and \( b \geq 0 \), i.e. agents do not get paid for decommitting. The contractor has to decide on decommitting when he knows his outside offer \( \bar{a} \) but does not know the contractee's outside offer \( \bar{b} \). Similarly, the contractee has to decide on decommitting when she knows her outside offer \( \bar{b} \) but does not know the

\(^2\)The framework can also be interpreted to model situations where the agents' cost structures for handling tasks and for getting tasks handled change e.g. due to resources going off-line or becoming back on-line.

\(^3\)Games where at least one agent's future is certain, are a subset of these games. In such games all of the probability mass of \( f(\bar{a}) \) and/or \( g(\bar{b}) \) is on one point.
contractor's. This seems realistic from a practical contracting perspective.

3.1 Nash equilibria for a given contract

One concern is that a rational agent is reluctant in decommitting because there is a chance that the other party will decommit, in which case the former agent gets freed from the contract, does not have to pay a penalty, and collects a penalty from the breacher. [Sandholm and Lesser, 1996] showed that despite such insincere decommitting the leveled commitment feature increases each contract party's expected payoff, and enables contracts in settings where no full commitment contract is beneficial to all parties.

The contractor decommits if he gets a low enough outside offer, e.g., he can get his task handled at a low cost. We denote his decommitting threshold by \( \bar{a}^* \), so his decommitting probability is

\[
\rho_a = \int_{-\infty}^{\bar{a}^*} f(\bar{a}) \, d\bar{a}
\]  

(1)

The contractee decommits if she gets a high enough outside offer, e.g., gets paid for handling a task. We denote her decommitting threshold by \( \bar{b}^* \), so her decommitting probability is

\[
\rho_b = \int_{\bar{b}^*}^{\infty} g(\bar{b}) \, d\bar{b}
\]  

(2)

3.2 Sequential decommitting games

In our sequential decommitting game, one agent has to reveal her decommitting decision before knowing whether the other party decommits. While our implementation analyzes both orders of decommitting, here we only discuss the setting where the contractee has to decide first. The case where the contractor decides first is analogous. There are two alternative leveled commitment contracts that differ on whether or not the agents have to pay the penalties if both decommit.

If the contractee has decommitted, the contractor's best move is not to decommit because \(-\bar{a} - a + b \leq -\bar{a} + b \) (because \( a \geq 0 \)). This also holds for a contract where neither agent has to pay a decommitment penalty if both decommit since \(-\bar{a} \leq -\bar{a} + b \). In the subgame where the contractee has not decommitted, the contractor's best move is to decommit if \(-\bar{c} - a > -\rho \), i.e.

\[
\bar{a}^* = \rho - a
\]  

(3a)

The contractee gets \( \bar{b} - b \) if she decommits, \( \bar{b} + a \) if she does not but the contractor does, and \( \rho \) if neither decommits. Thus the contractee decommits
if $\bar{b} - b > p_b(\bar{b} + a) + (1 - p_b)\rho$. If $p_b = 1$, this is equivalent to $-b > a$ which is false because $a \geq 0$ and $b \geq 0$. In other words, if the contractee surely decommits, the contractor does not. On the other hand, the above is equivalent to

$$\bar{b} > \rho + \frac{b + a - \rho p_a}{1 - p_a} \overset{\text{def}}{=} \bar{b}^* \text{ when } p_a < 1$$  \hspace{1cm} (4a)

### 3.3 Simultaneous decommitting games

In our simultaneous decommitting games, agents have to reveal their decommitment decisions simultaneously. We first discuss the variant where both have to pay the penalties if both decommit. The contractor decommit if $p_b \cdot (-\bar{a} + b - a) + (1 - p_b)(-\bar{a} - a) > p_b \cdot (-\bar{a} + b) + (1 - p_b)(-\rho)$. If $p_b = 1$, this equates to $a < 0$, but we already ruled out contracts where an agent gets paid for decommitting. On the other hand, this equates to

$$\bar{a} < \rho - \frac{a}{1 - p_b} \overset{\text{def}}{=} \bar{a}^* \text{ when } p_b < 1$$  \hspace{1cm} (3b)

The contractee decommits if $(1 - p_a)(\bar{b} - b) + p_a(\bar{b} - b + a) > (1 - p_a)\rho + p_a(\bar{b} + a)$. If $p_a = 1$, this equates to $b < 0$, but we ruled out contracts where an agent gets paid for decommitting. However, this equates to

$$\bar{b} > \rho + \frac{b}{1 - p_a} \overset{\text{def}}{=} \bar{b}^* \text{ when } p_a < 1$$  \hspace{1cm} (4b)

In another type of simultaneous decommitting game, neither agent has to pay if both decommit. The contractor decommits if $p_b \cdot (-\bar{a}) - (1 - p_b)(-\bar{a} - a) > p_b \cdot (-\bar{a} + b) + (1 - p_b)(-\rho)$. If $p_b = 1$, this equates to $b < 0$, but we already ruled out contracts where an agent gets paid for decommitting. On the other hand, this equates to

$$\bar{a} < \rho - a - \frac{a - \rho p_b}{1 - p_b} \overset{\text{def}}{=} \bar{a}^* \text{ when } p_b < 1$$  \hspace{1cm} (3c)

The contractee decommits if $(1 - p_a)(\bar{b} - b) + p_a \bar{b} > (1 - p_a)\rho + p_a(\bar{b} + a)$. If $p_a = 1$, this equates to $a < 0$, but we ruled out contracts where an agent gets paid for decommitting. However, this equates to

$$\bar{b} > \rho + \frac{b - \rho p_a}{1 - p_a} \overset{\text{def}}{=} \bar{b}^* \text{ when } p_a < 1$$  \hspace{1cm} (4c)

### 3.4 Contract optimizer implementation

For each game, calculating the Nash equilibria amounts to solving the simultaneous equations (3) and (4) which use (1) and (2). Given an equilibrium, it is easy to compute the agents’ expected payoffs under the contract. Furthermore, we have developed algorithms for choosing the contract price and
the decommitting penalties in a way that maximizes the sum of the agent’s expected payoffs, and divides the gains fairly, or in any other way as long as both parties benefit. That optimization algorithm takes into account that the agents decommit insincerely in Nash equilibrium. To begin, the user inputs \( f \) and \( g \) graphically or textually. The contract is optimized separately for each one of the protocols, which vary based on who has to reveal her decommitting decision first—the simultaneous protocols are also considered—and whether or not the agents have to pay the penalties if both decommit. The optimal contracts for each protocol are then presented to the user, see http://ecommerce.cs.wustl.edu/contracts.html.

4 eExchangeHouse: A safe exchange planner

Contract execution is more difficult in electronic commerce than physical commerce because the parties may be anonymous and can disappear easily. For example, a shopping agent can vanish by simply killing its process, and litigation is infeasible unless the other contract party knows which real-world entity the agent represented. Another problem is the lack of uniform laws on electronic commerce and particularly agent-mediated commerce in different countries.

An important aspect of contract execution is making sure that the seller gets paid, and that the buyer gets the goods. The risk is that once one party has received the item, he may be motivated to vanish without delivering his part of the contract. This could be avoided by a trusted third party that takes the payment and goods, and carries out the transaction only after all parties have delivered their part to the intermediary. Today’s electronic commerce implements a coarse one-sided variant of this where the third party takes the payment into escrow, and releases it to the seller only after the buyer has verified receipt of the goods. A disadvantage of these third party escrow companies like i-Escrow Inc. and Trade-Direct is the cost of running such an intermediary, which is recovered as fees - currently about 5% of the contract price - from the contract parties.

A method to tackle this problem without third parties was developed by [Sandholm, 1997]. The exchange is divided into chunks where each party delivers a small amount at a time, and the exchange proceeds with such alternation. The method is most suitable for settings where dividing the
goods into chunks is relatively inexpensive, such as is often the case for example with information goods and computational services. A sequence is called safe if each party is motivated to follow the exchange at every step in anticipation of the profit from the rest of the exchange instead of vanishing with what the other party has delivered so far. Specifically, a safe sequence can be executed in subgame perfect Nash equilibrium. Some chunkings allow a safe sequence while others do not. Similarly, some sequences of delivering given chunks are safe while others are not.

As part of eMediator, we built a safe exchange planner called eExchange-House. In the case where a single divisible good is exchanged, the user inputs a graph of how the buyer’s valuation accrues as a function of how much has been delivered, and another graph that shows how the seller’s cost accrues. In the case of multiple distinguishable goods, the user lists how many goods are to be exchanged, and how many units of each good. For each possible state of the exchange (units of good 1 delivered × units of good 2 delivered × ...) the user inputs the the buyer’s valuation and the seller’s cost. Note that combining indistinguishable goods into units of a single good significantly reduces the state space since within each good, only the number of units delivered matters, not which ones. Finally, the user inputs how much gain the seller is willing to forego to avoid possible reputation costs from defecting in the exchange, and similarly, how much gain the buyer is willing to forego. Based on this input, the planner finds a safe chunking that minimizes the number of chunks and a safe chunk sequence if they exist. If they do not exist, the user is alerted of this. The chunking algorithms and the chunk sequencing algorithms are highly nontrivial, and are the topic of a longer future paper. They are currently being coded to be joined with the GUI that is already complete.

5 Conclusions

The eMediator prototype exemplifies several features that can facilitate more efficient ecommerce in the future. Its configurable auction house includes a variety of generalized combinatorial auctions, price setting mechanism, bidding methods, mobile agents, and user support for choosing an auction type. The leveled commitment contract optimizer determines the optimal contract price and decommitting penalties for a variety of leveled commitment pro-
tocols, taking into account that rational agents will decommit insincerely. Finally, the safe exchange planner enables unenforced anonymous exchanges by dividing the exchange into chunks and sequencing those chunks to be delivered safely in alternation between the buyer and the seller. Each one of the three mechanisms exhibits an interesting interplay between algorithms and game theoretic incentive engineering. In the future we are planning to add to eMediator next generation reputation services, product evaluation methods, a nonmanipulable voting server, coalition formation support, and a meta-auction that sits on top of other auctions on the web.

6 Acknowledgments

I thank Qianbo Huai for programming most of the auction house component, eAuctionHouse. I thank Qianbo Huai, Alan Huffman, and Pradeep Gore for their significant contributions to the development of NOMAD, the mobile agent component. I thank Sandeep Sikka, Samphel Norden, and Yun-hong Zhou for their contributions to analyzing and programming the leveled commitment contract optimizer.

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